

# Ranking on Cross-Domain Manifold for Sketch-based 3D model Retrieval

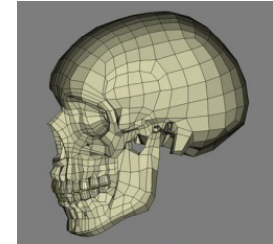
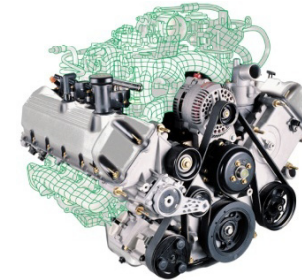


Takahiko Furuya, Ryutarou Ohbuchi  
University of Yamanashi

# Introduction



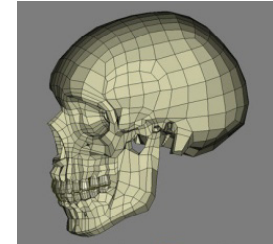
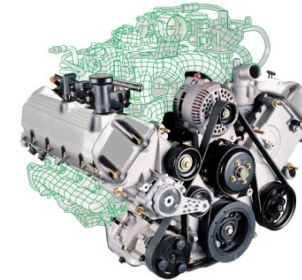
- 3D models are widely used.
  - Mechanical CAD, Games,...
  - 3D range scanners, 3D printers,...
  - User generated.
    - Trimble 3D warehouse, ...
- 3D model retrieval is essential.
  - High retrieval accuracy.
  - Efficiency.
  - Ease of use.



# Introduction



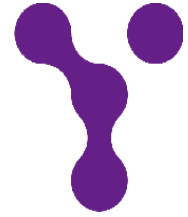
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- 3D model retrieval is essential.
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accurate  
and  
easy to use

# Why sketch-based ?



## ■ Keywords

- ✓ Accessible for most people.
- ✗ 3D models lack textual tags.

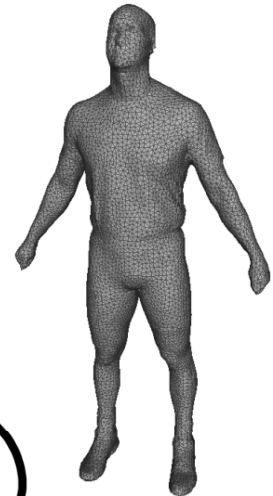
## ■ 3D model

- ✓ Sufficiently accurate for certain applications.
- ✗ 3D models often unavailable.

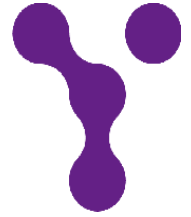
## ■ 2D sketch

- ✓ Accessible for most people.
- ✓ Intuitively specify 2D shape.
- ✗ Inaccurate.
  - Even the best method yields MAP = 11% using SHREC 2013 benchmark.

human search



# Cross-domain matching problem

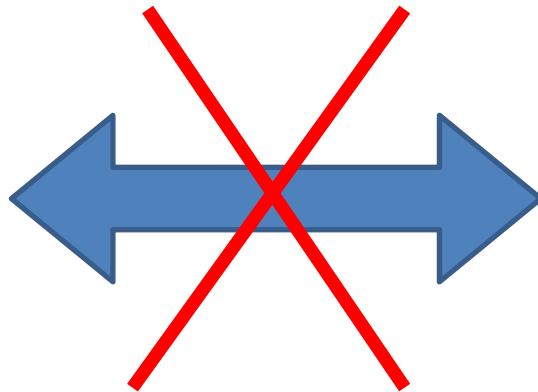


- How do we compare a 2D sketch and a 3D model?

Can't be compared directly.

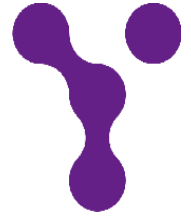


2D sketch



3D model

# Cross-domain matching problem



- Approach 1 : Image feature-based comparison.
  - Renders 3D models into lines.
    - e.g., Suggestive contour [DeCarlo03], ...
  - Adopted by most.



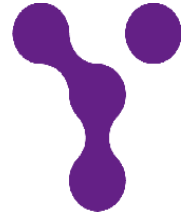
2D sketch

Can be compared.



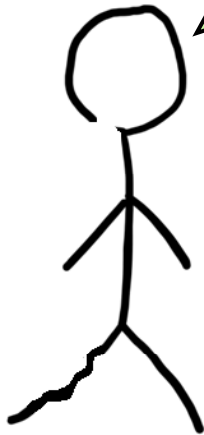
2D sketch-like image

# Cross-domain matching problem



- Approach 1 : Image feature-based comparison.

Can't handle abstraction,  
semantic influence and noise.

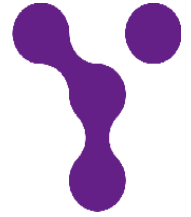


2D sketch

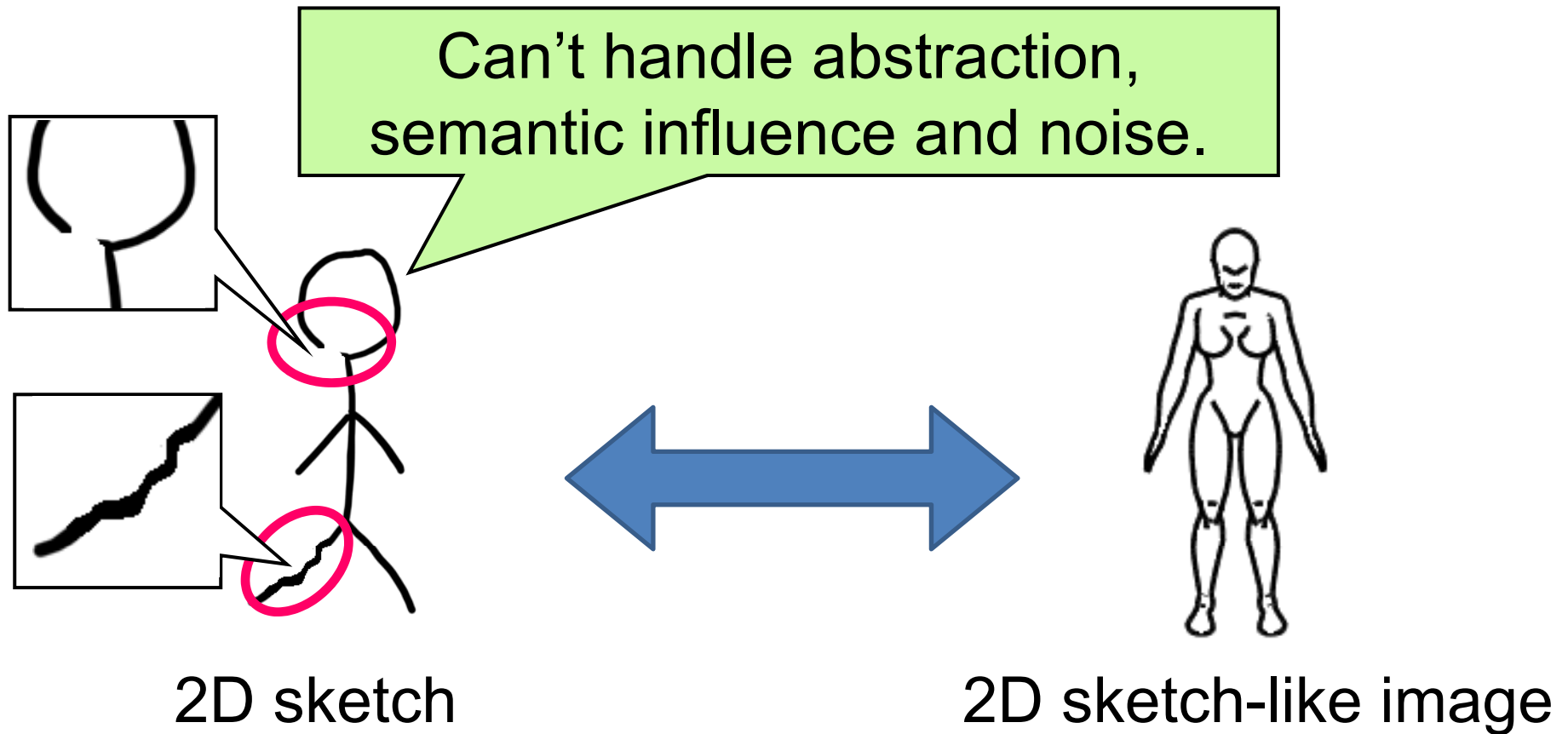


2D sketch-like image

# Cross-domain matching problem

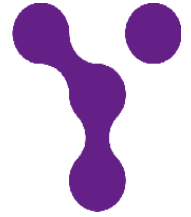


- Approach 1 : Image feature-based comparison.

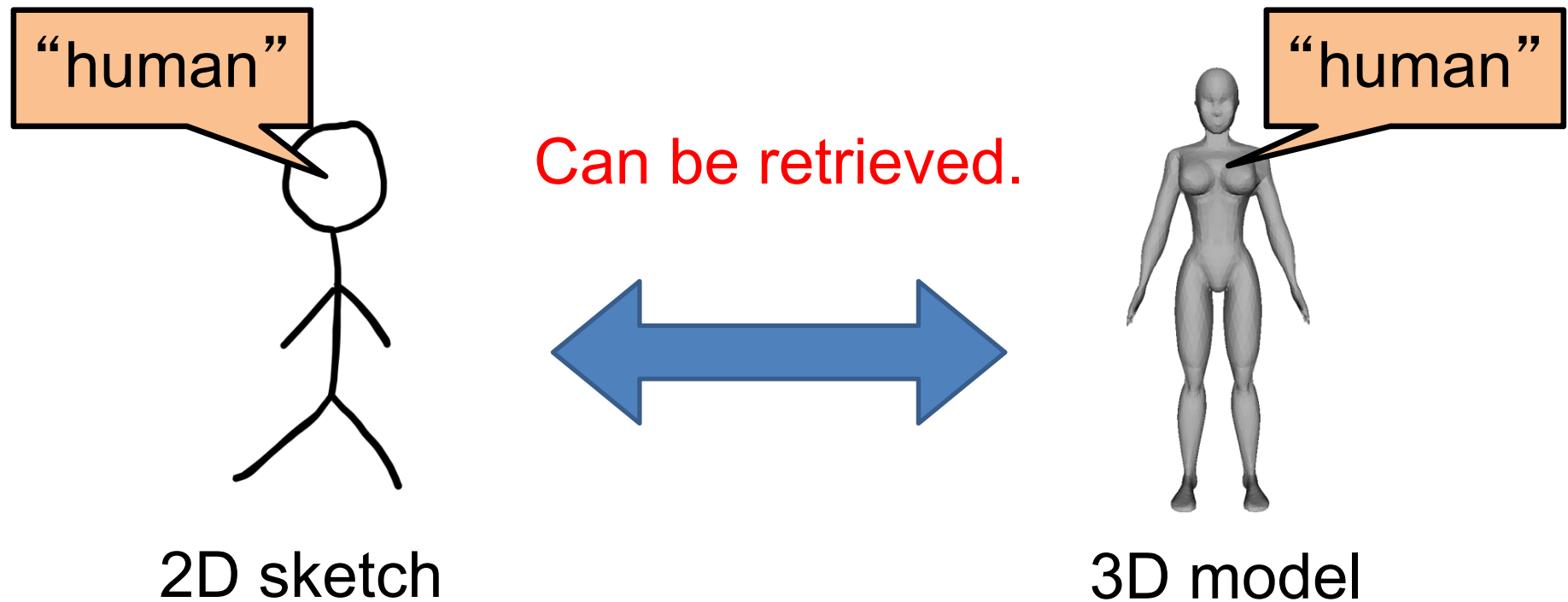




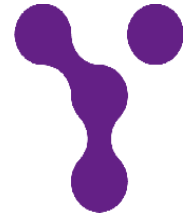
# Cross-domain matching problem



- Approach 2 : Semantic label-based comparison.

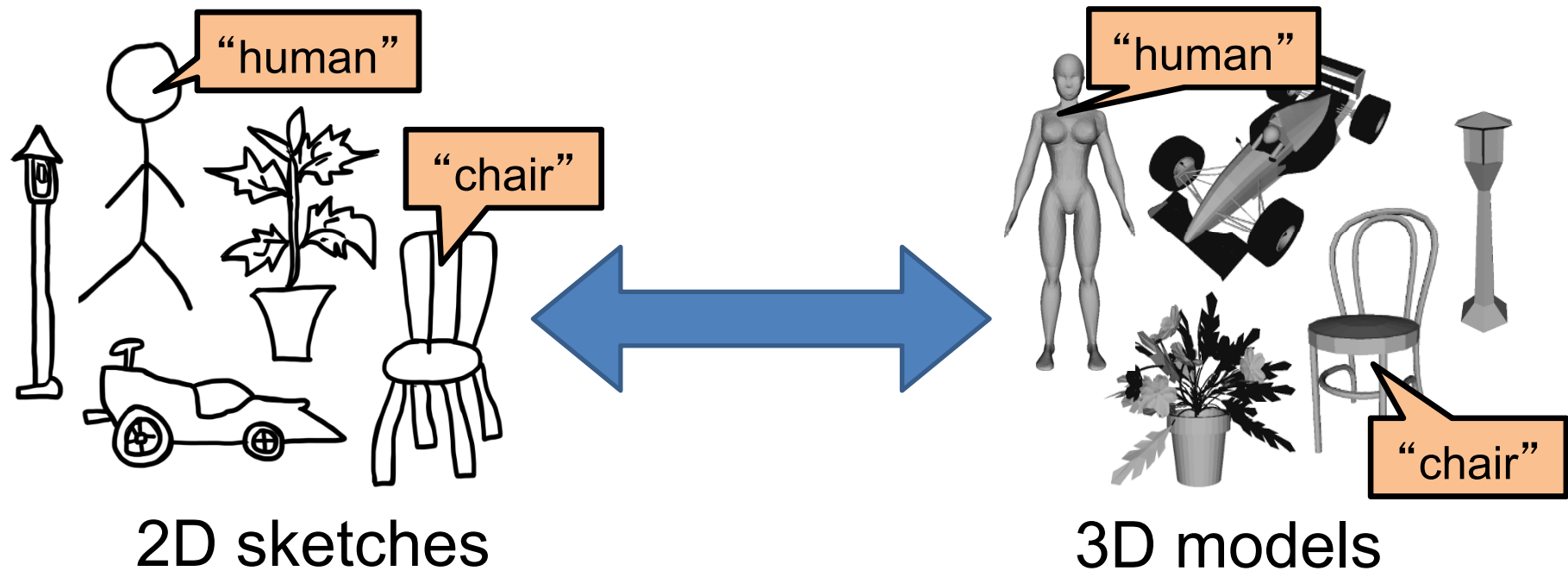


# Cross-domain matching problem



- Approach 2 : Semantic label-based comparison.

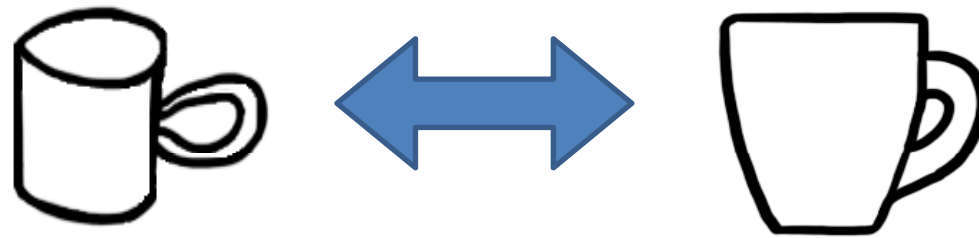
Learning sparse labels is difficult.



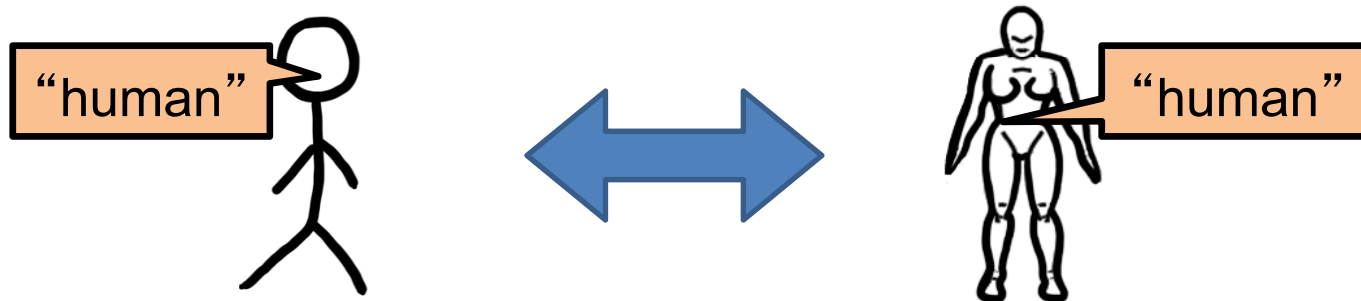
# Our approach



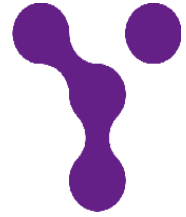
- **Combination of features and labels.**
  - ✓ Matching by image features.



- ✓ Matching by semantic labels.



# Outline

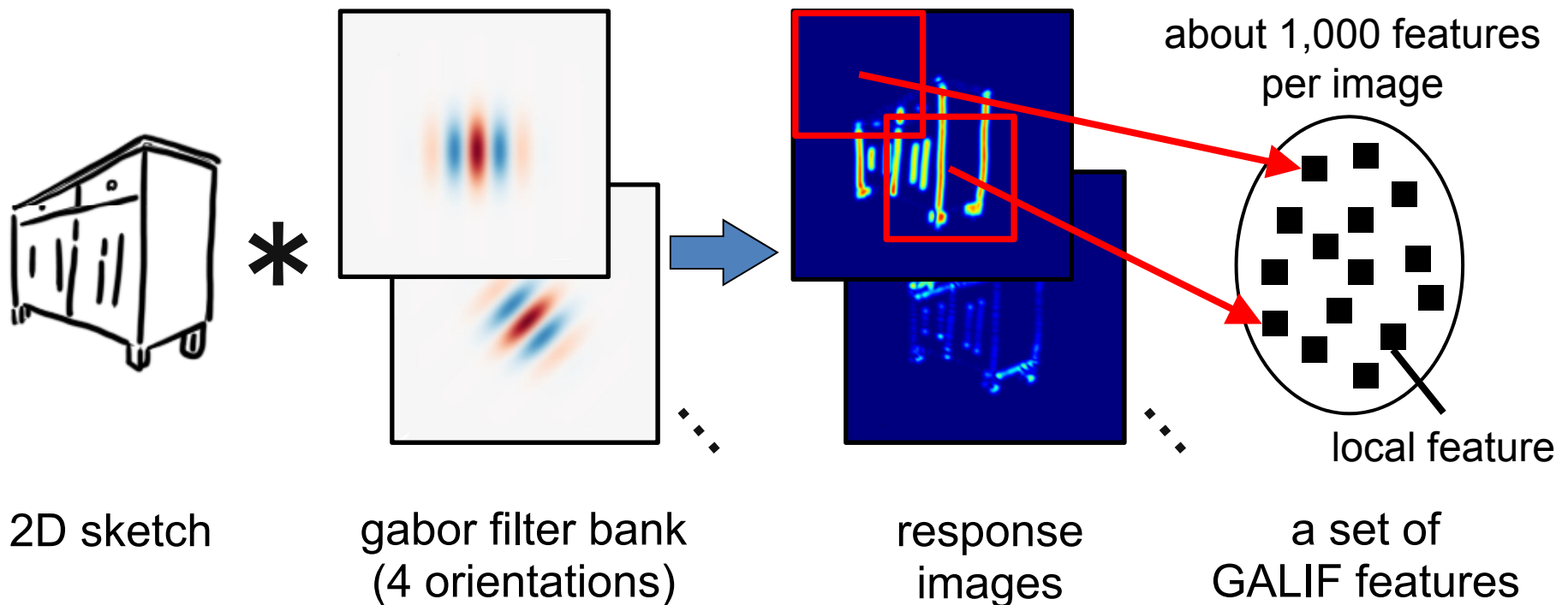


- Related work
  - BF-GALIF [Eitz12]
    - Algorithm for sketch-based 3D model retrieval
  - Manifold Ranking [Zhou03]
    - Algorithm for distance metric learning
  
- Proposed method
  
- Experiments and results
  
- Conclusion and future work

# Related work : Sketch-to-3D model matching algorithm BF-GALIF [Eitz12]



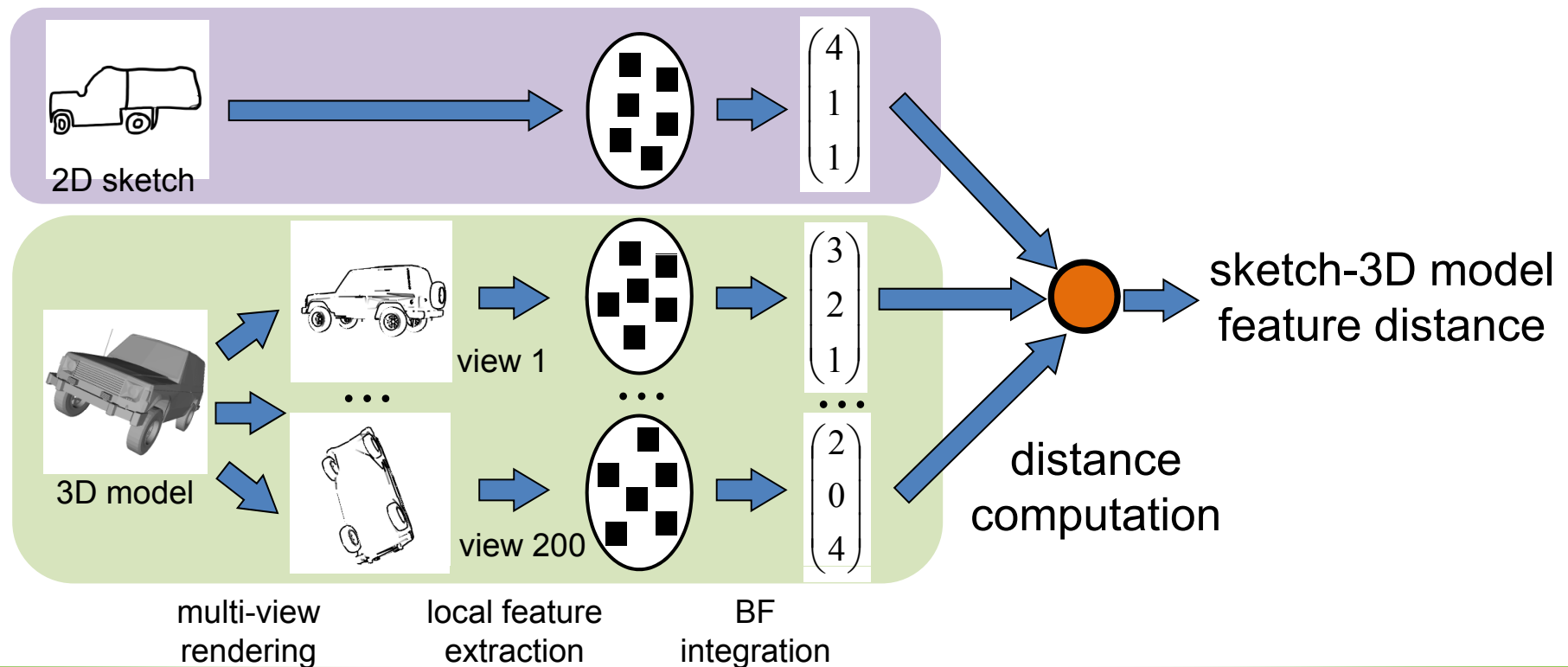
- Efficiently compares sets of local features.
  1. **Densely extracts Gabor filter-based local features.**
  2. Integrates local features into a vector by Bag-of-Features.



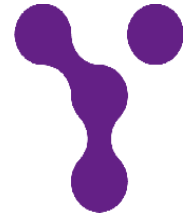
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Related work : Sketch-to-3D model matching algorithm  
BF-GALIF [Eitz12]



- Efficiently compares sets of local features.

Robust against articulation of 2D shape.

Among the most accurate methods.

Yet, insufficient ...

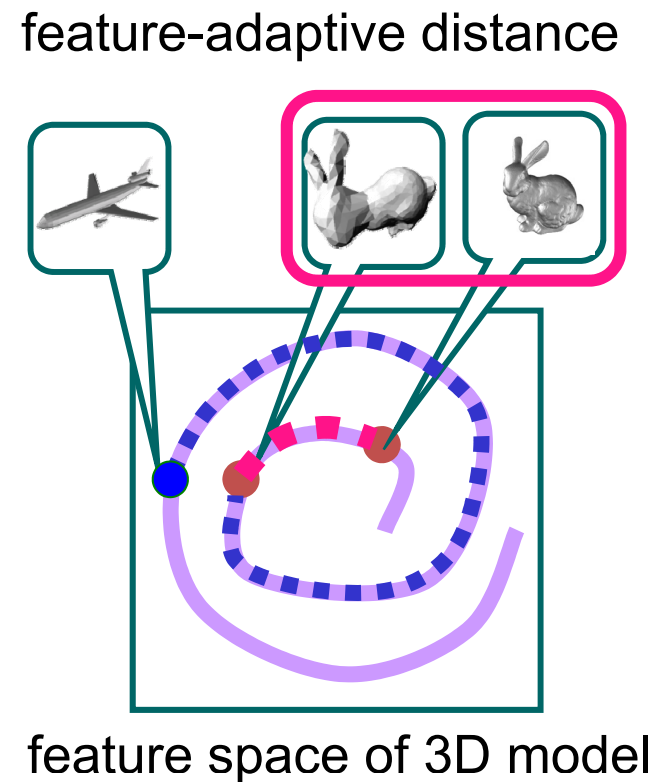
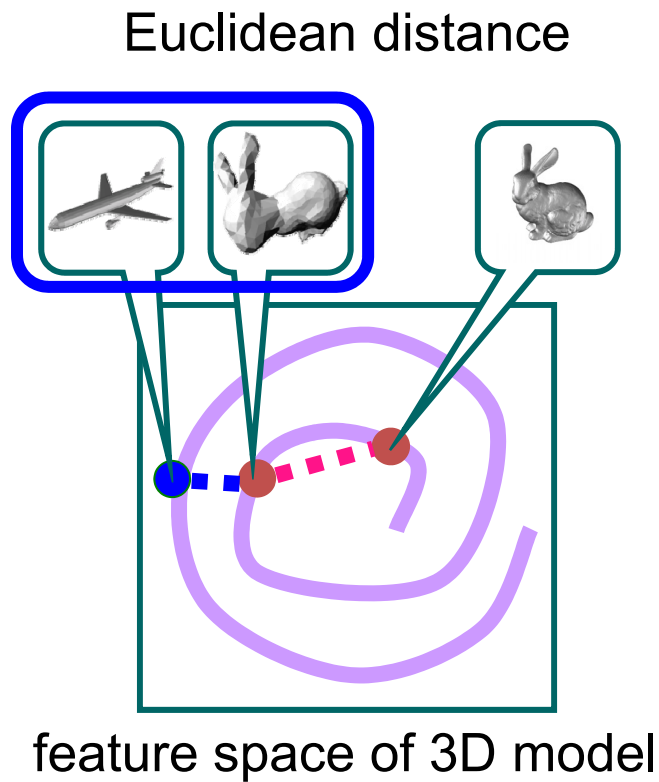
Our approach

- better feature comparison.
- semantic labels.

# Improving single-domain feature comparison



- Learns feature-adaptive distance metric on manifold.

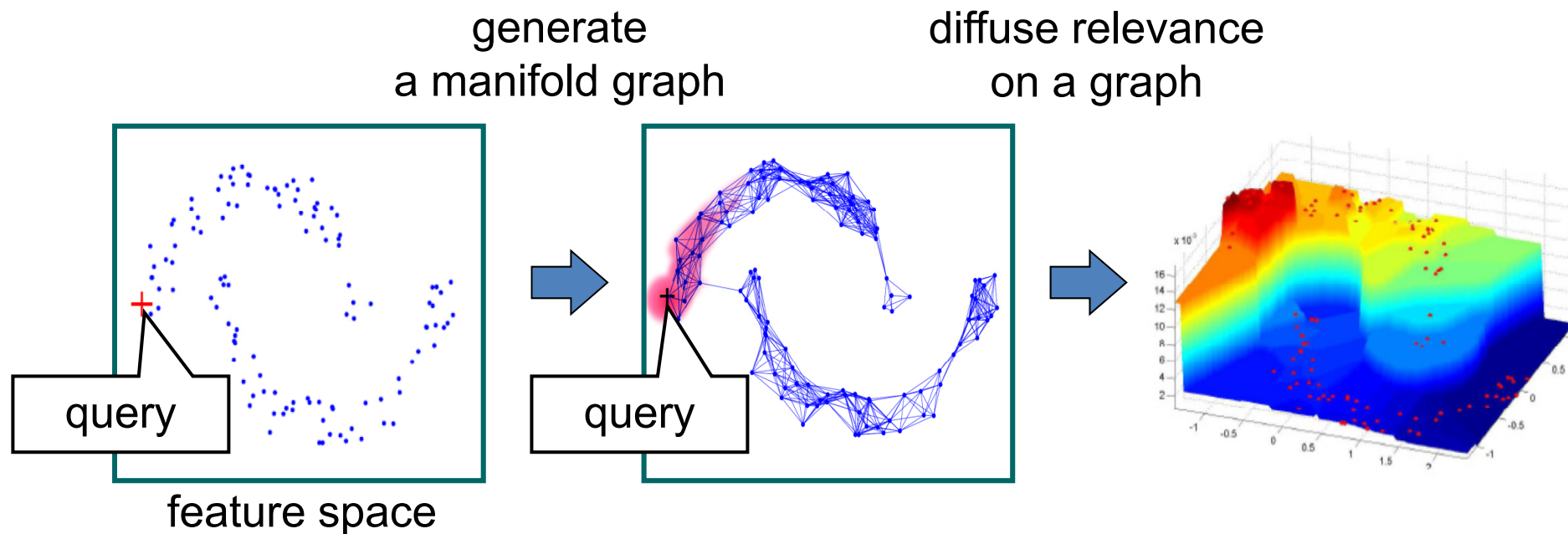






## Related work : Distance metric learning Manifold Ranking [Zhou03]

- Diffusion distance on a feature manifold graph.



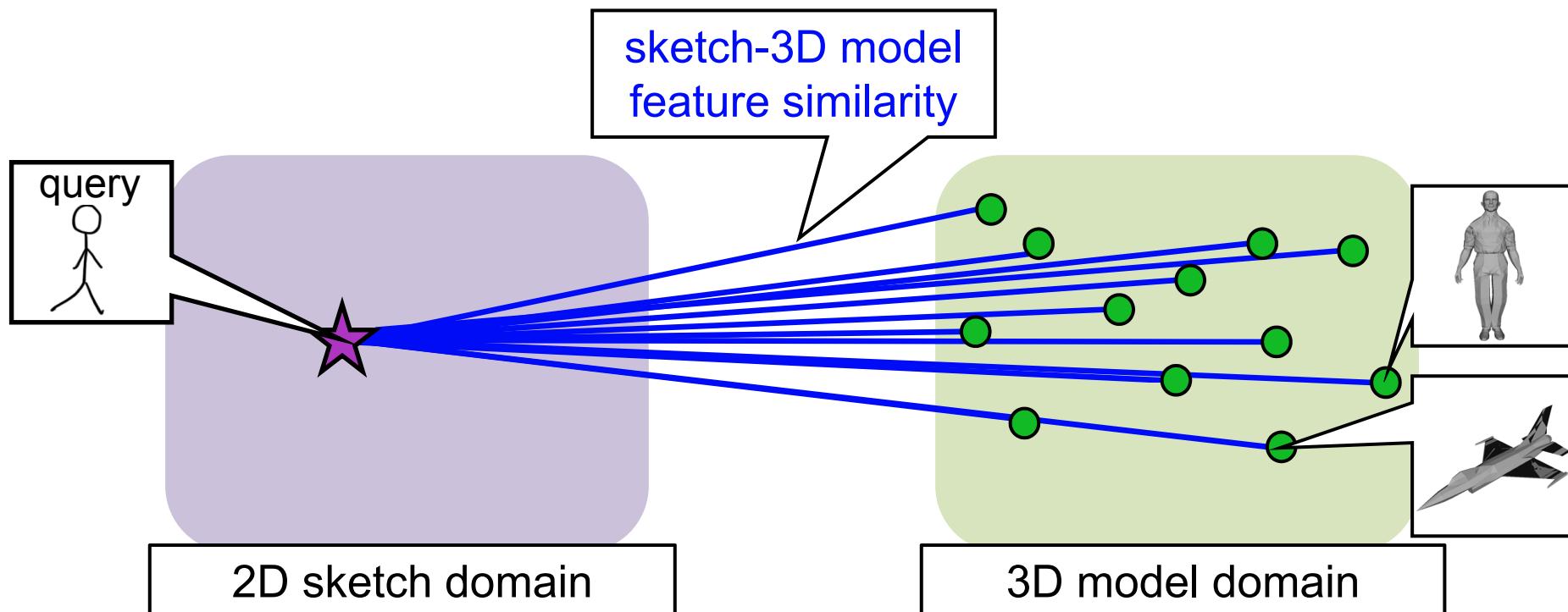
### Our approach

- extends Manifold Ranking to cross-domain.

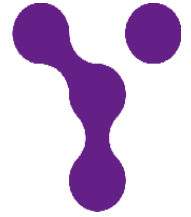
# Improving cross-domain feature comparison



- BF-GALIF [Eitz12]
  - Structure of feature manifold is ignored.



# Outline

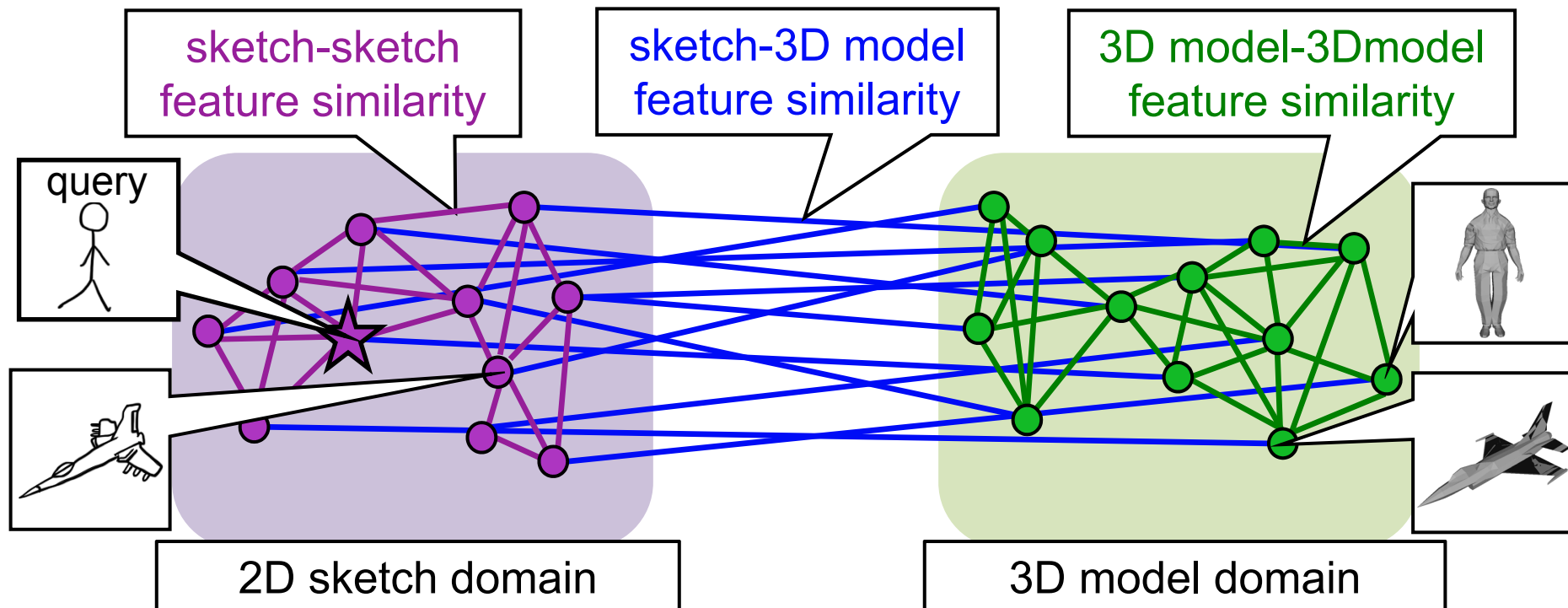


- Related work
- **Proposed method**
  - Cross-Domain Manifold Ranking (CDMR) algorithm
- Experiments and results
- Conclusion and future work

# Improving cross-domain feature comparison



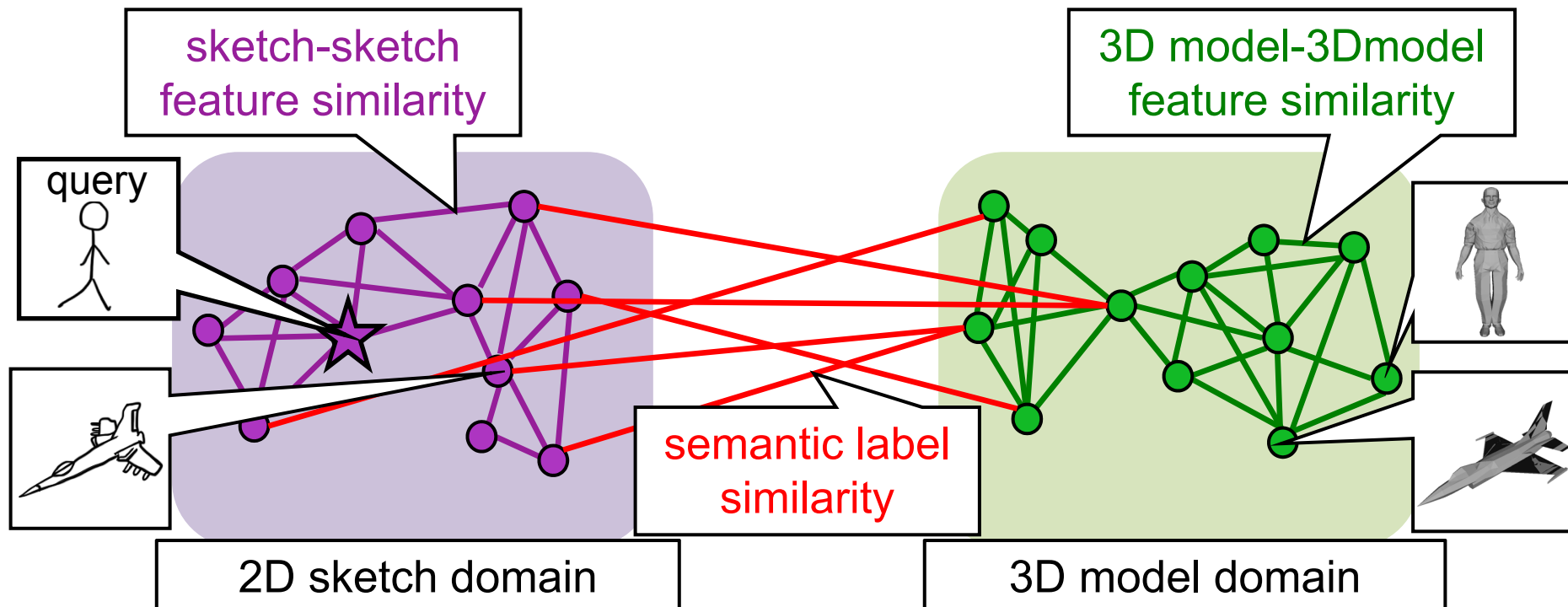
- Ranking by diffusion distance on a Cross-Domain Manifold (CDM).



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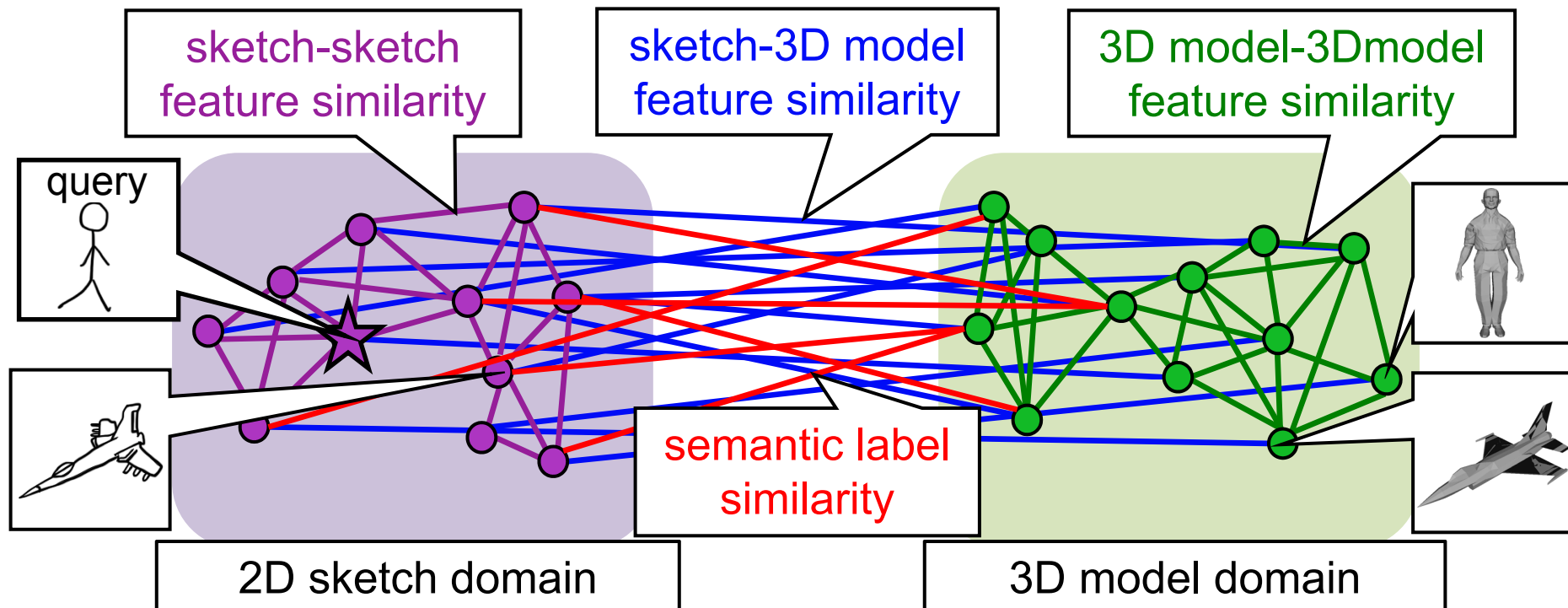
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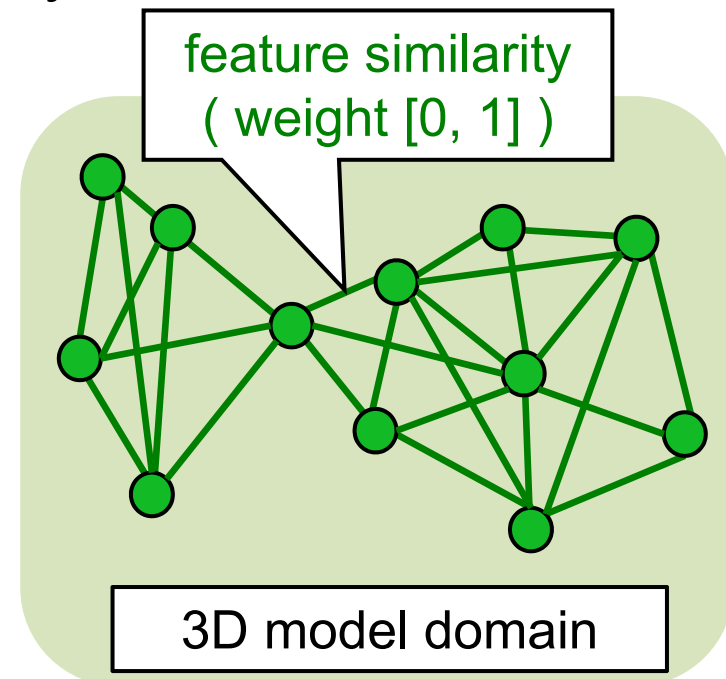
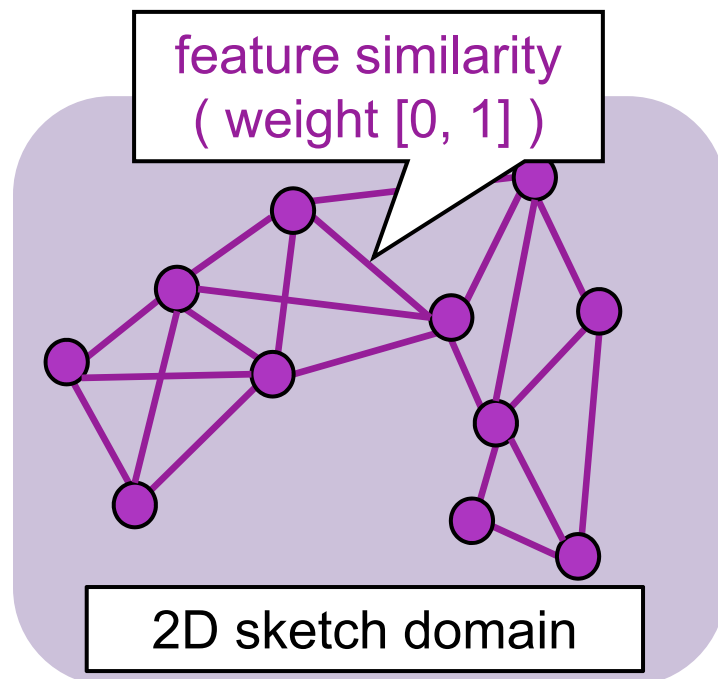


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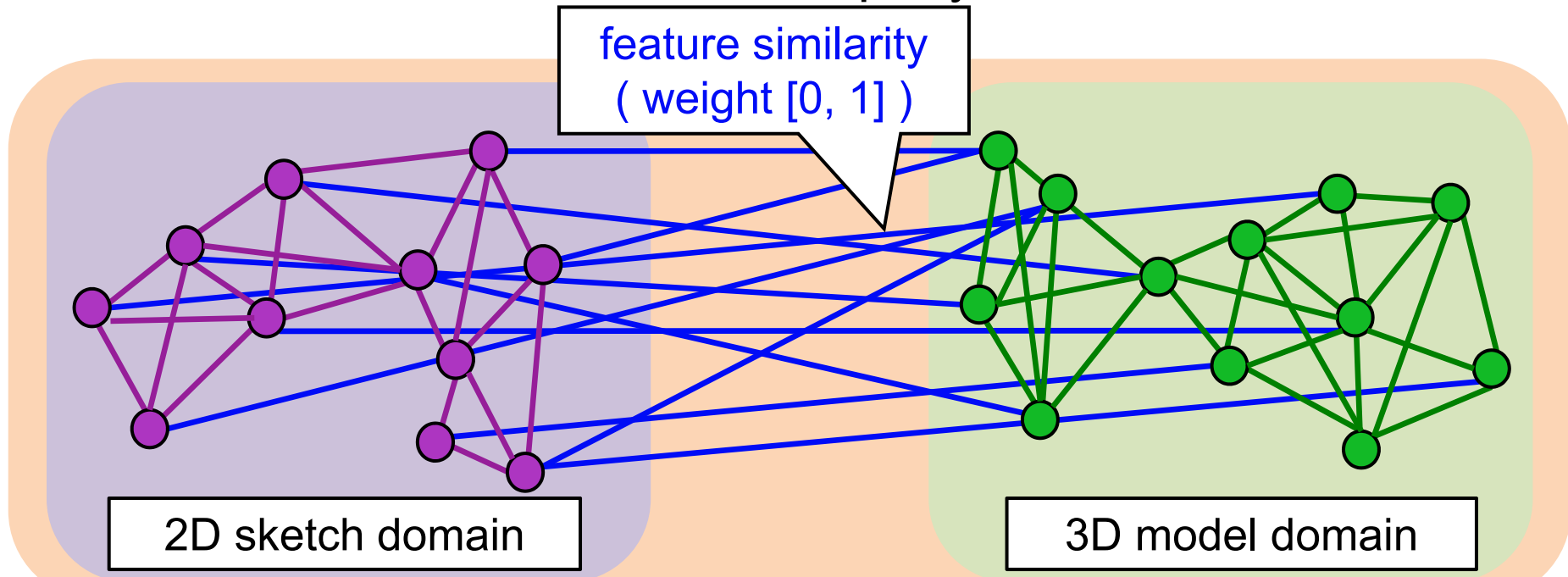


- Ranking by diffusion distance on the CDM.
  - Generates a feature manifold on each domain.
  - Links the two manifolds by feature and label similarity.
  - Diffuses relevance from the query.





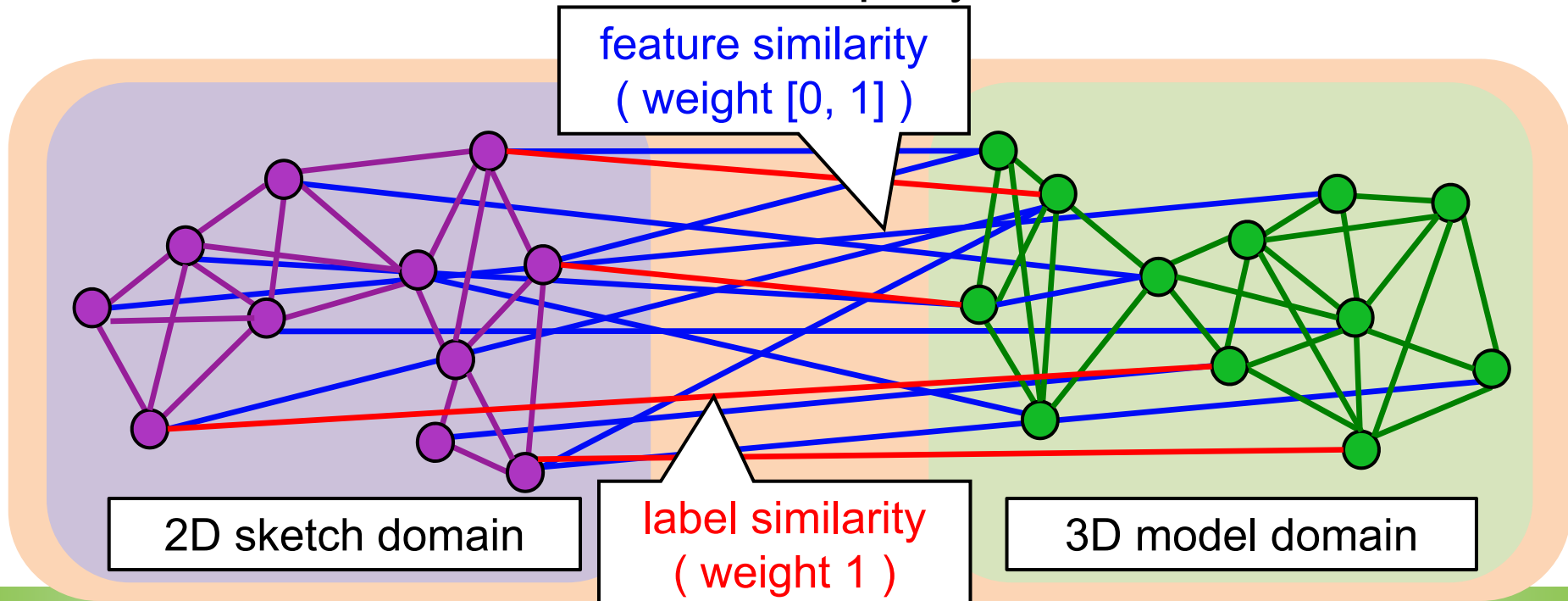
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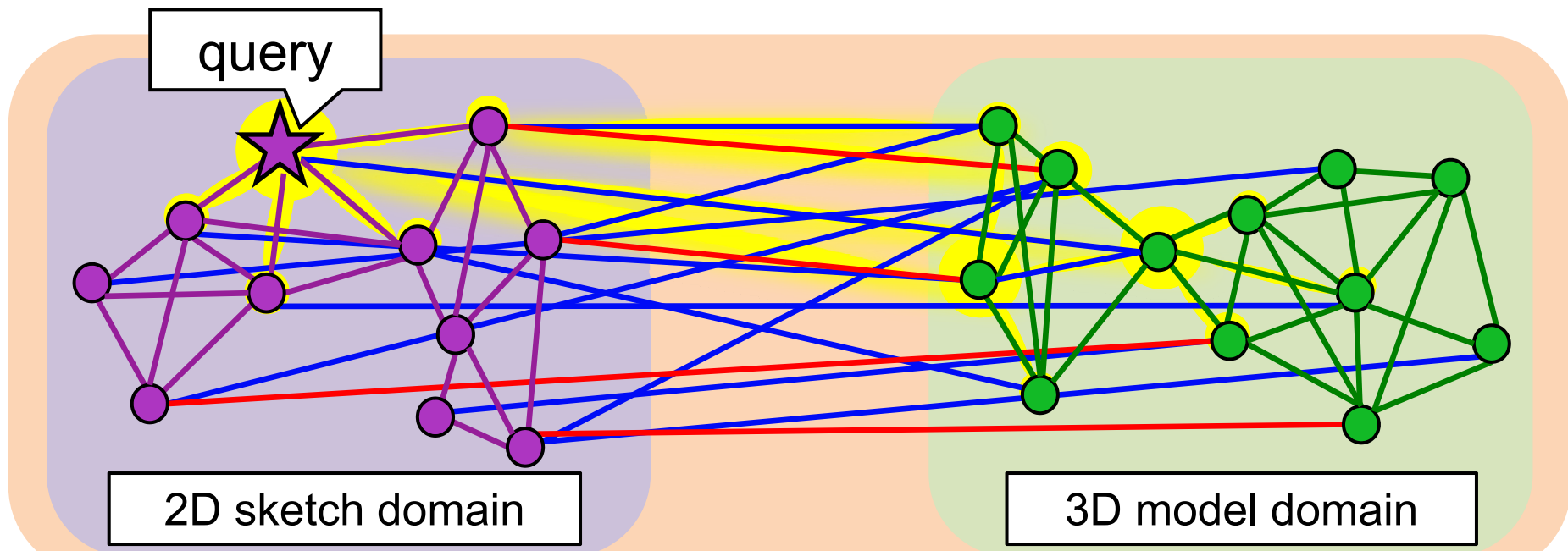


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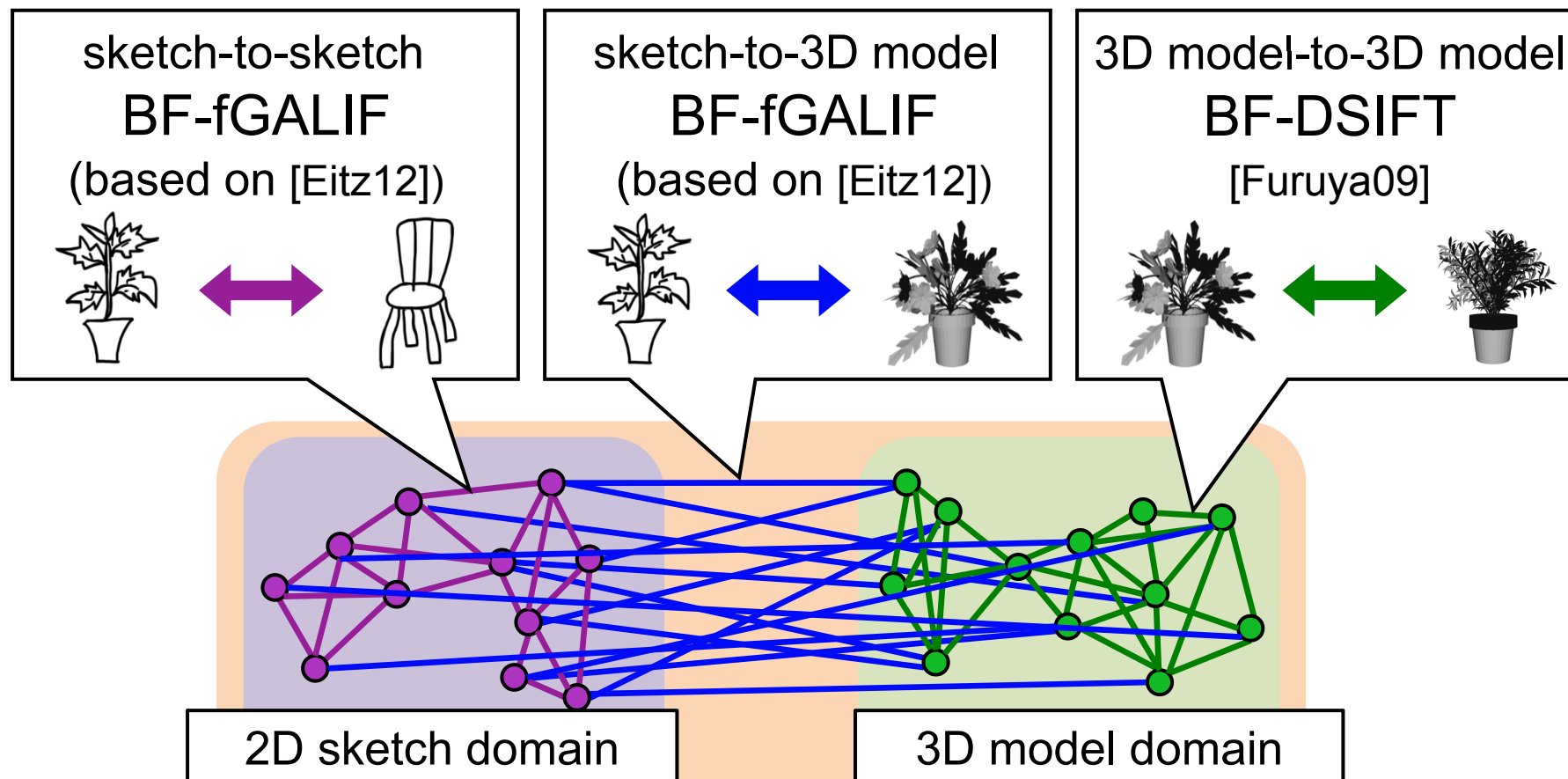
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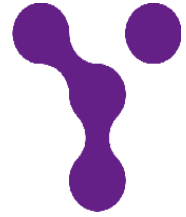


# Proposed method Cross-Domain Manifold Ranking (CDMR)

## ■ Feature comparison methods.



# Outline



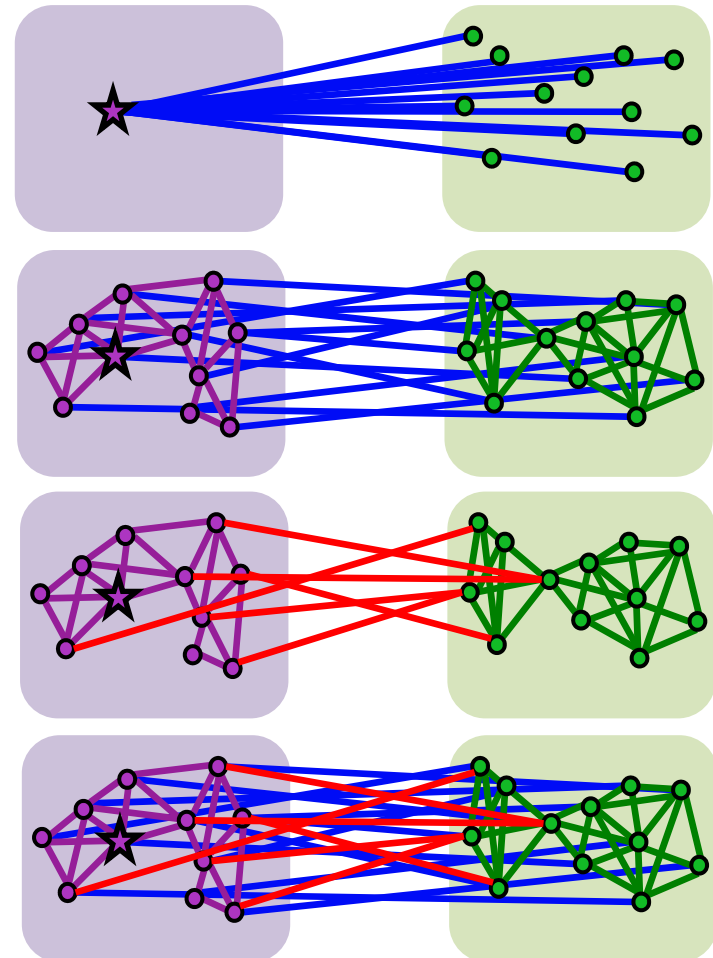
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# Experiments



## ■ Evaluate retrieval accuracy.

- BF-fGALIF (≐ [Eitz12])
  - No distance metric learning.
  - Baseline
- CDMR-BF-fGALIF (F)
  - Unsupervised learning.
- CDMR-BF-fGALIF (L)
  - Supervised learning.
- CDMR-BF-fGALIF (F+L)
  - Semi-supervised learning.



# Experiments

## Benchmark databases



### ■ S-PSB [Eitz12]

• Test set (90 categories)

907 sketches

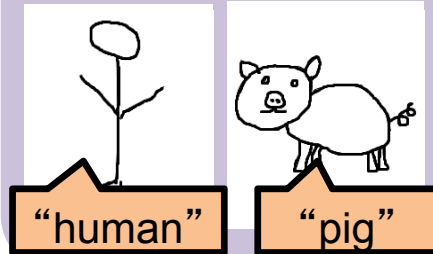


907 models

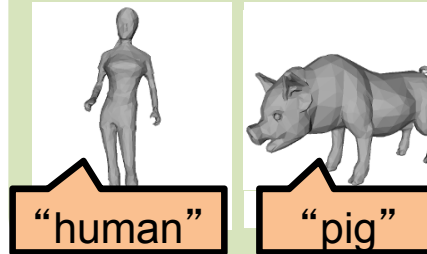


• Training set (92 categories)

907 sketches



907 models



Difficult to learn labels.

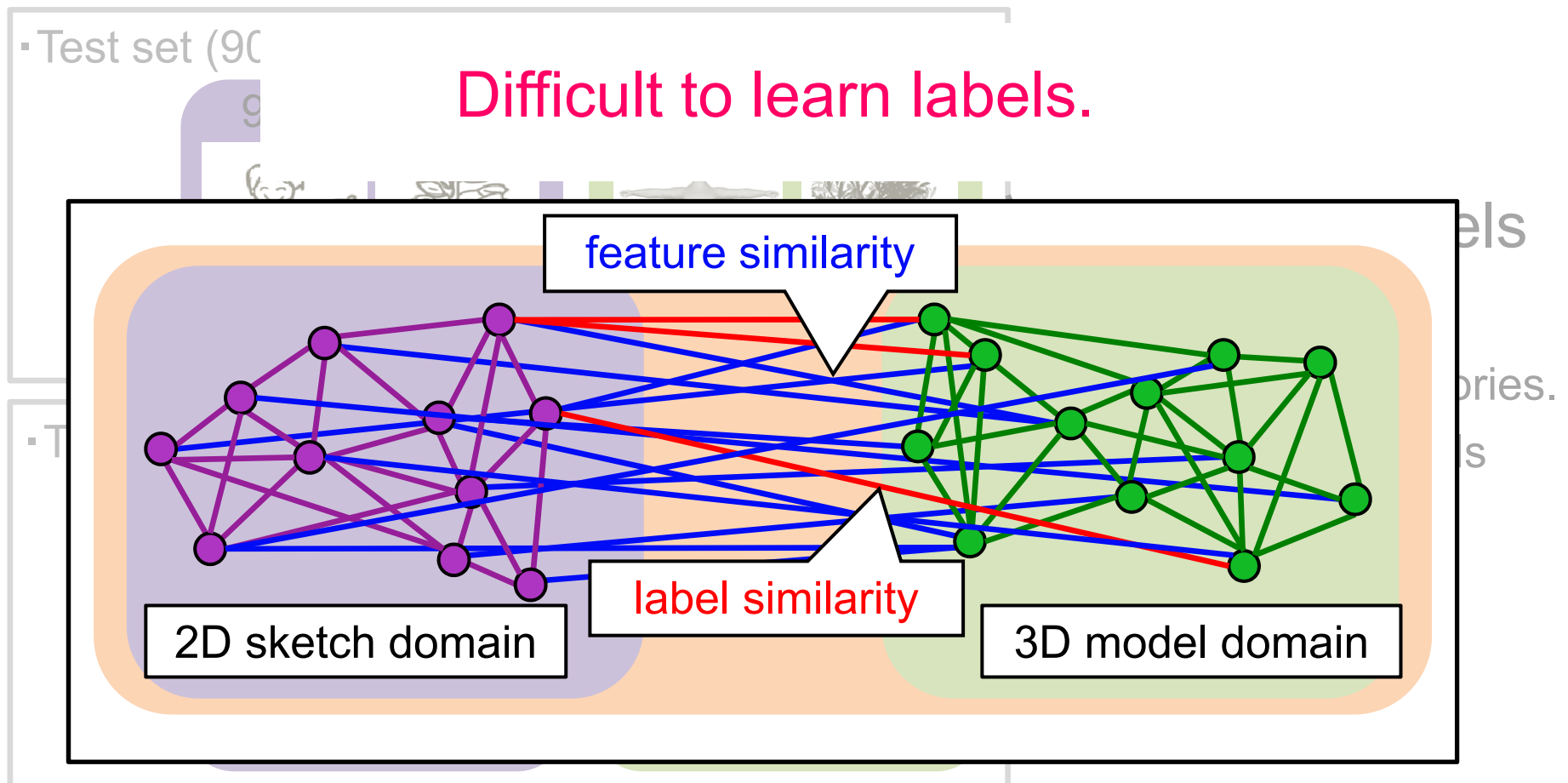
- 21 shared categories.
- As few as 4 labels per category.

# Experiments

## Benchmark databases



### ■ S-PSB [Eitz12]

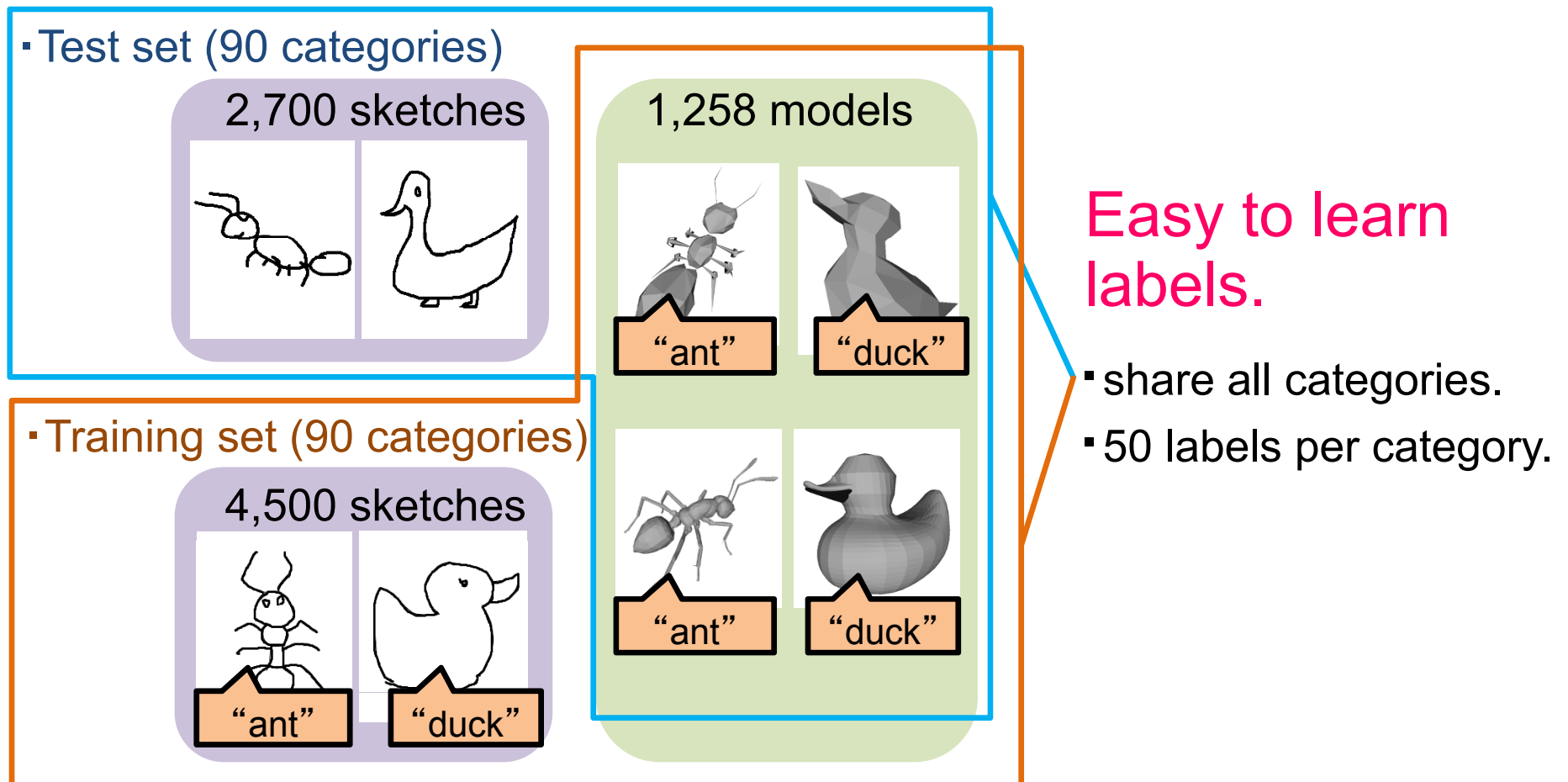


# Experiments

## Benchmark databases



- SHREC2013 sketch-based 3D shape retrieval (SH13) [Li13]



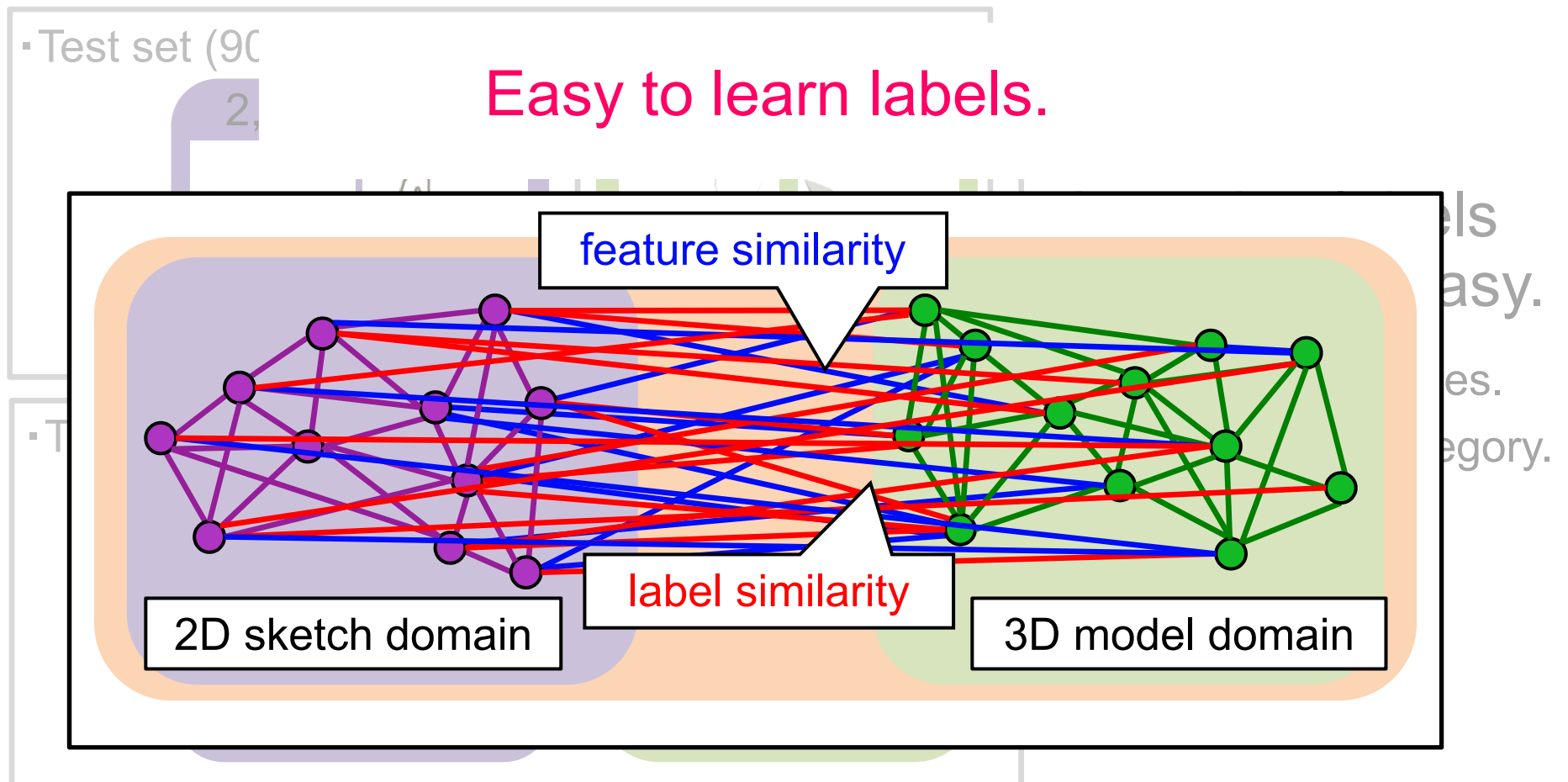


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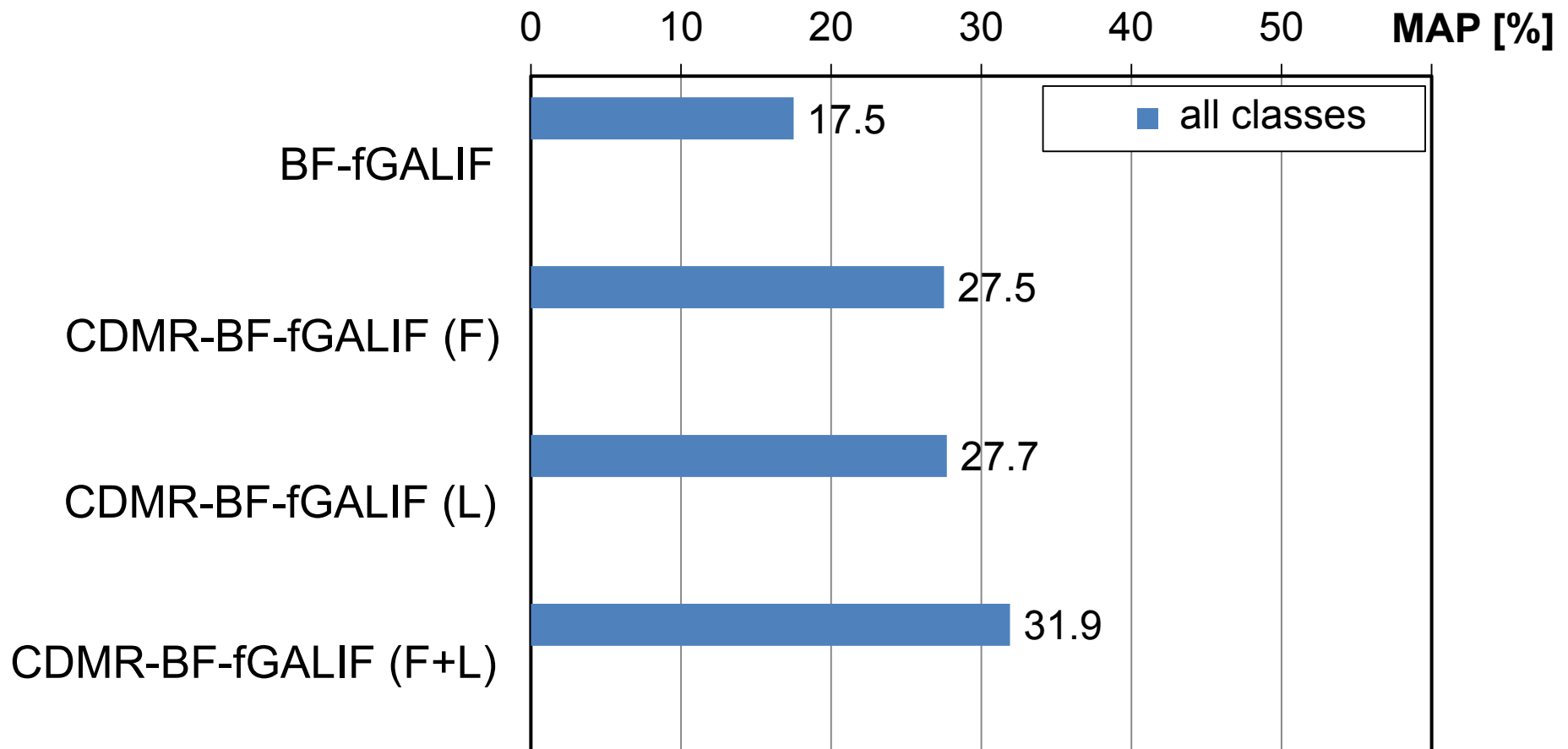


# Experimental results

## Effectiveness of CDMR for S-PSB



- CDMR is effective.

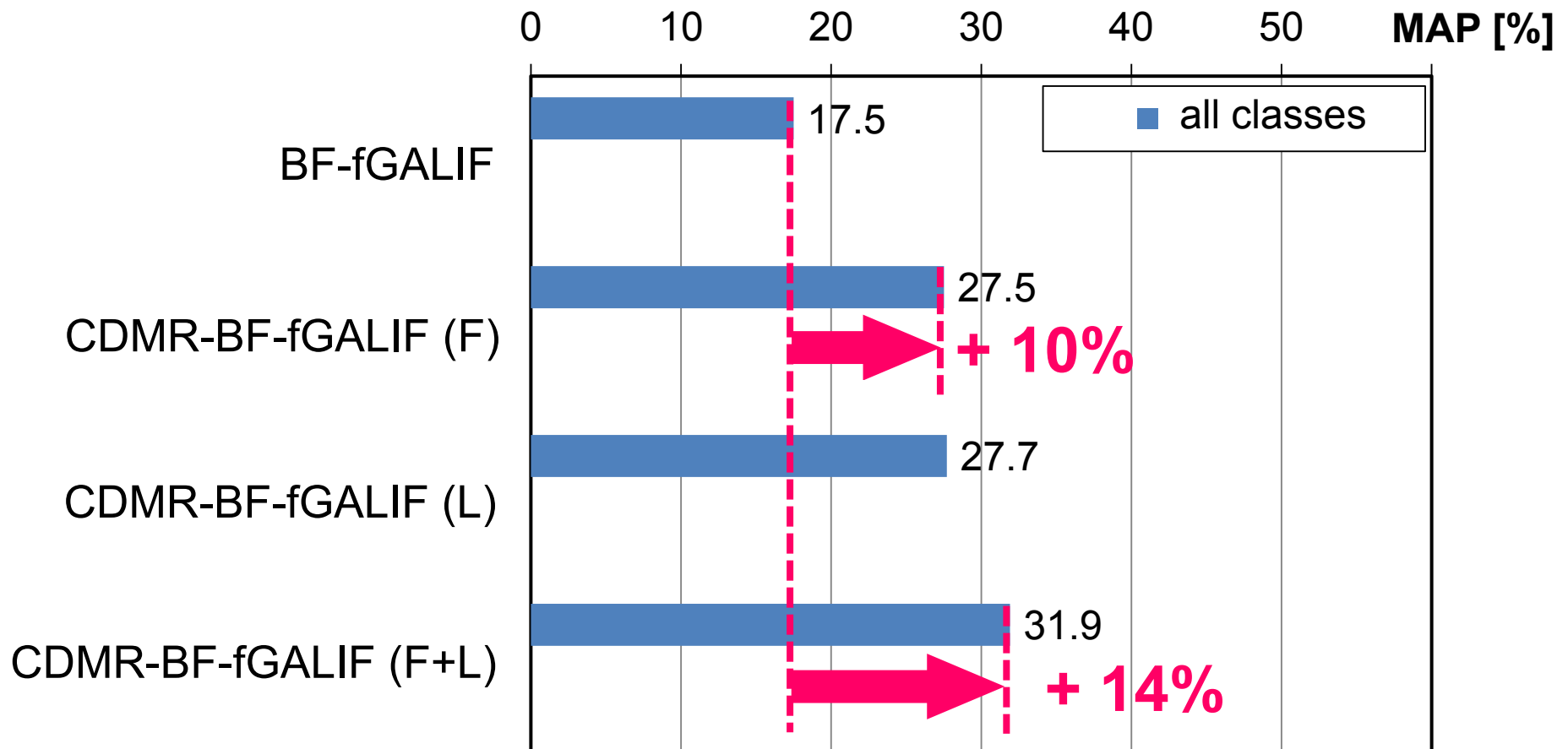


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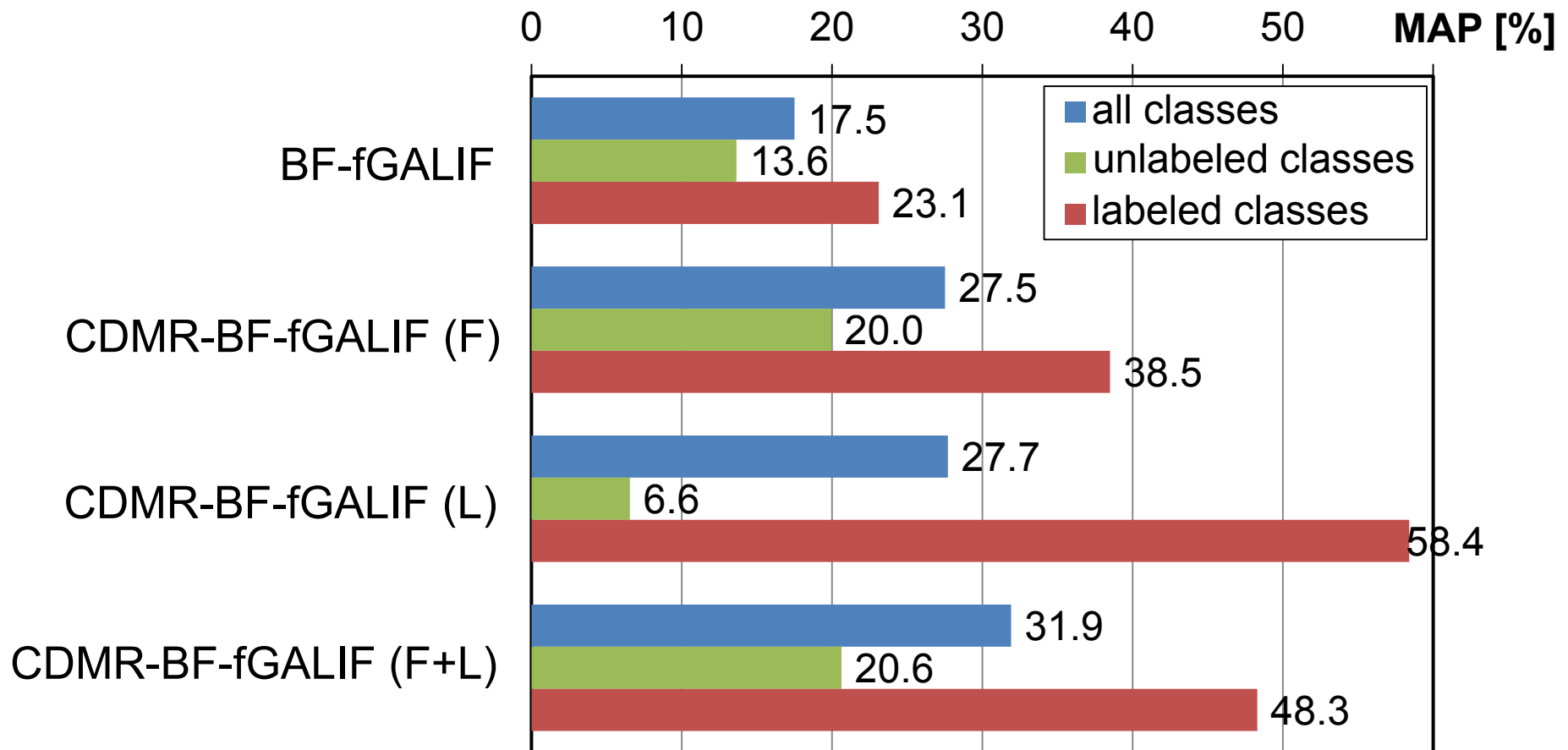


# Experimental results

## Effectiveness of CDMR for S-PSB



- CDMR (F+L) effectively learns sparse labeling.

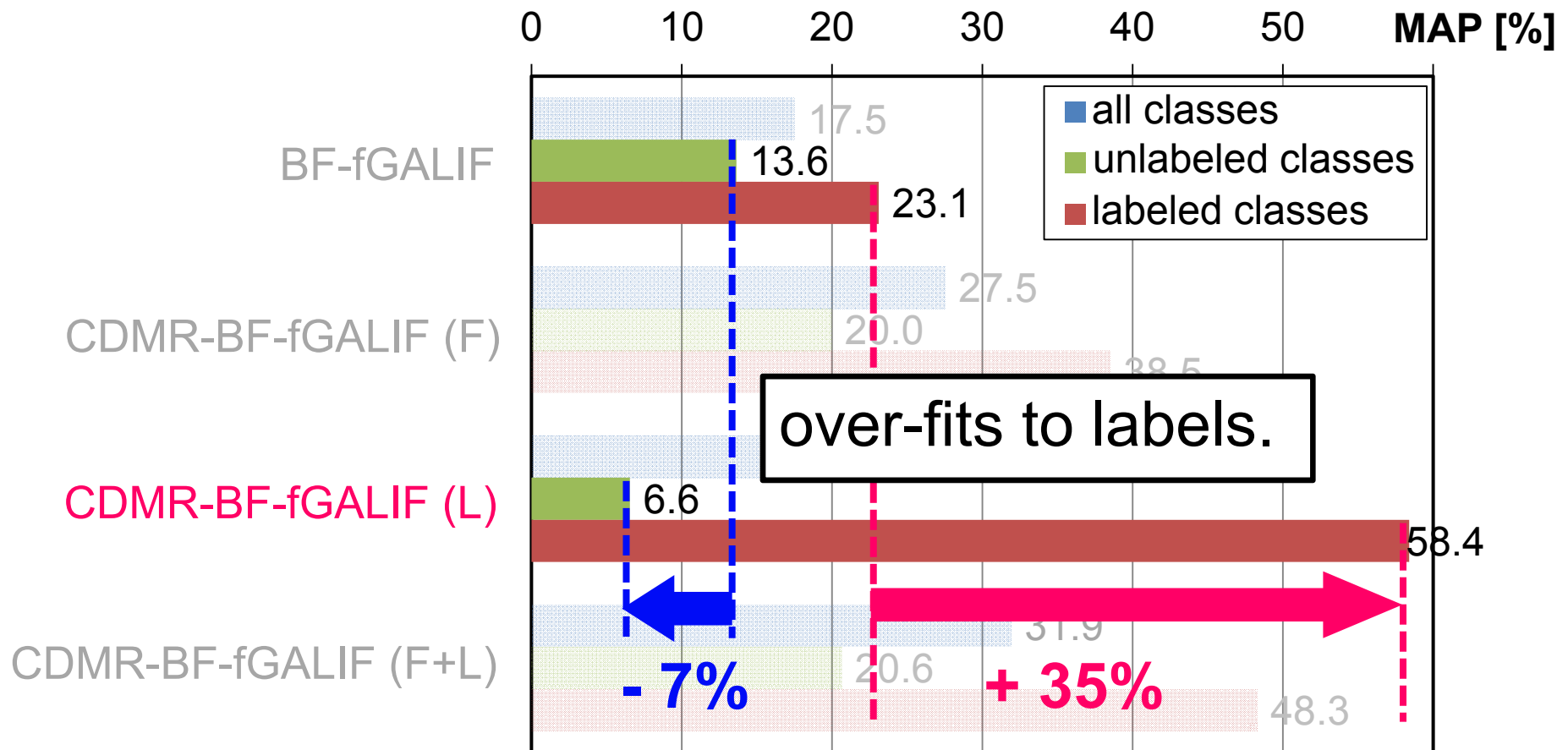


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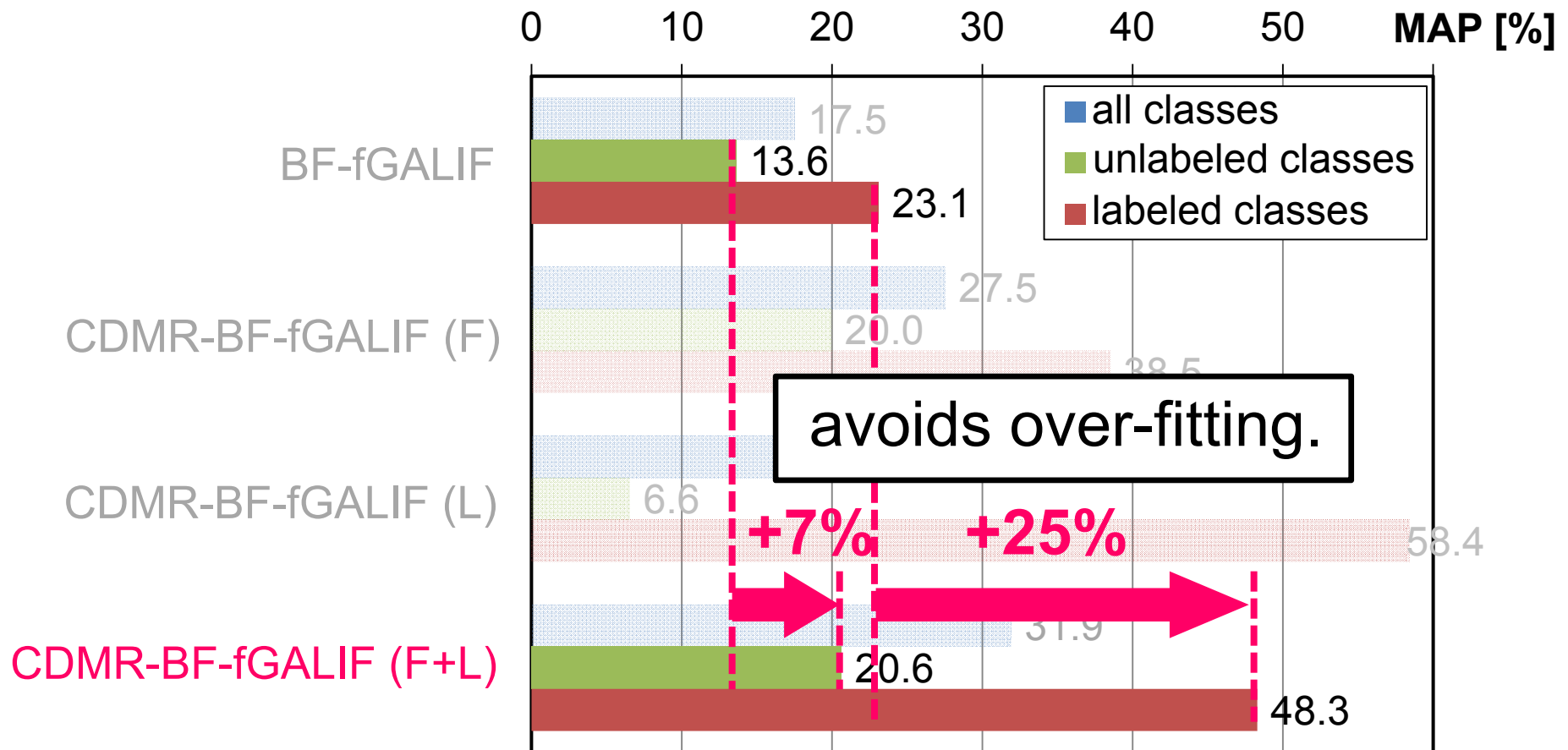


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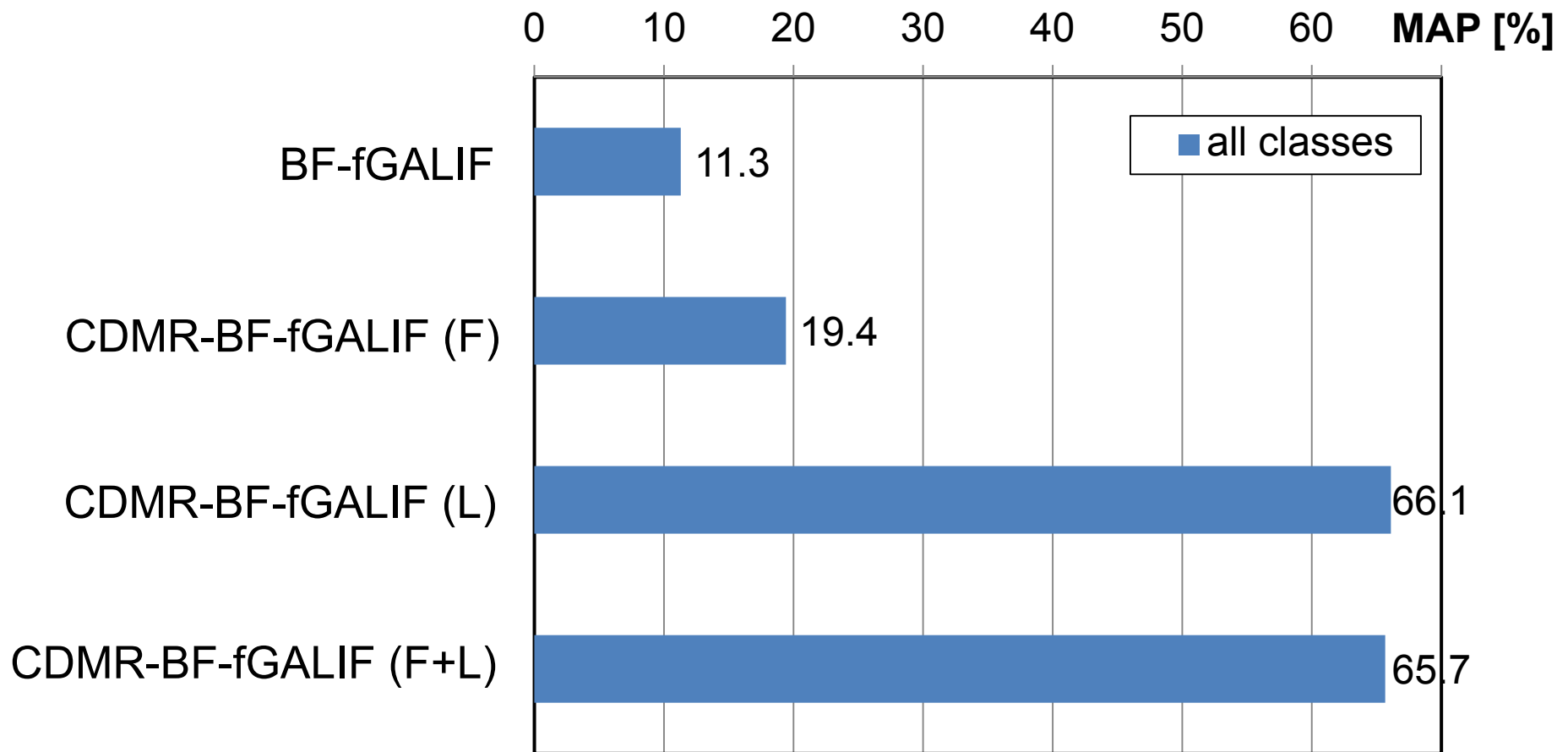


# Experimental results

## Effectiveness of CDMR for SH13



- Large improvement of MAP due to dense labeling.

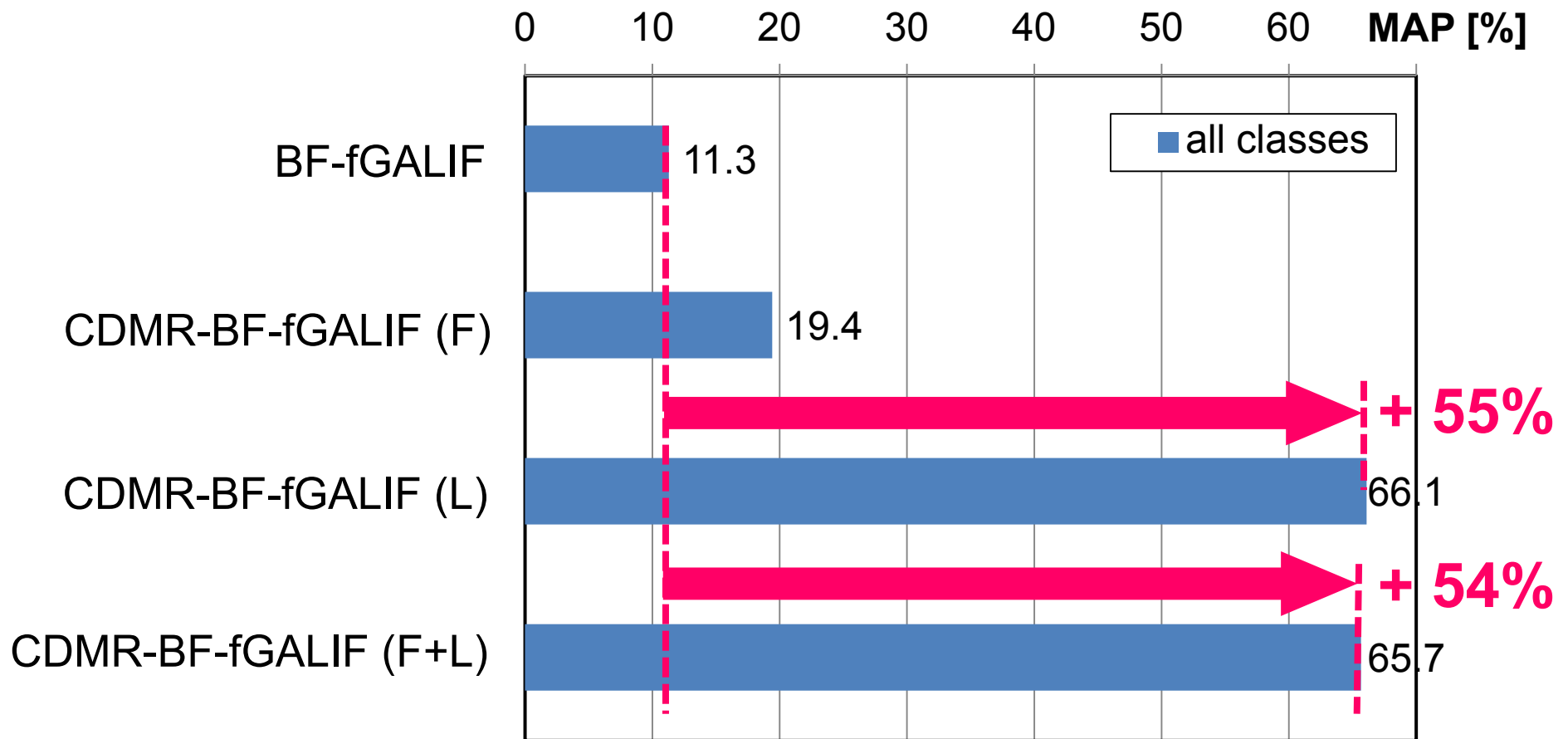


# Experimental results

## Effectiveness of CDMR for SH13

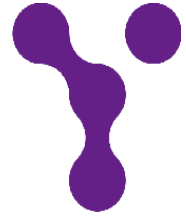


- Large improvement of MAP due to dense labeling.





# Conclusion and Future work



## ■ Conclusion

- More accurate sketch-based 3D model retrieval.
  - Cross-Domain Manifold Ranking (CDMR)
    - Combines feature similarity and semantic similarity.
    - Outperforms previous methods.

## ■ Future work

- Faster computation (e.g., approximation of diffusion).
- More accurate feature comparison.