## Ranking on Cross-Domain Manifold for Sketch-based 3D model Retrieval



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#### 2013/11/25

#### Introduction

- 3D models are widely used.
  - Mechanical CAD, Games,...
  - 3D range scanners, 3D printers,...
  - User generated.

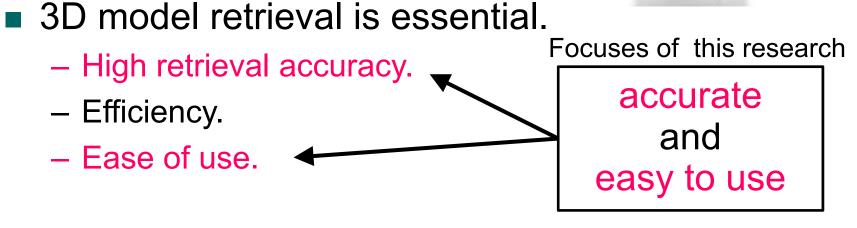
– Efficiency.

- Ease of use.

- High retrieval accuracy.

• Trimble 3D warehouse, ...

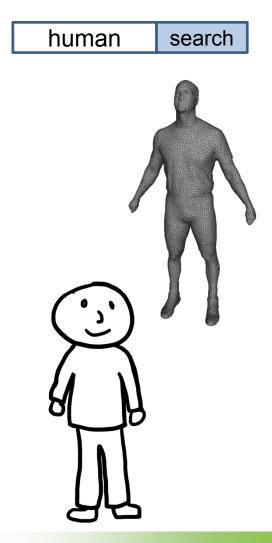






### Why sketch-based ?

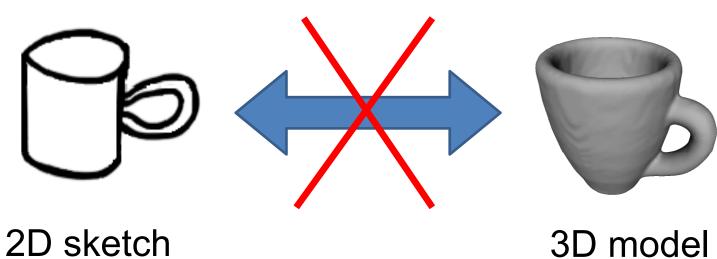
- Keywords
  - ✓ Accessible for most people.
  - × 3D models lack textual tags.
- 3D model
  - ✓ Sufficiently accurate for certain applications.
  - × 3D models often unavailable.
- 2D hand-drawn sketch
  - ✓ Accessible for most people.
  - ✓ Intuitively specify 2D shape.
  - × Inaccurate.
    - Even the best method yields MAP = 11% using SHREC 2013 benchmark.





How do we compare a 2D sketch and a 3D model?

#### Can't be compared directly.





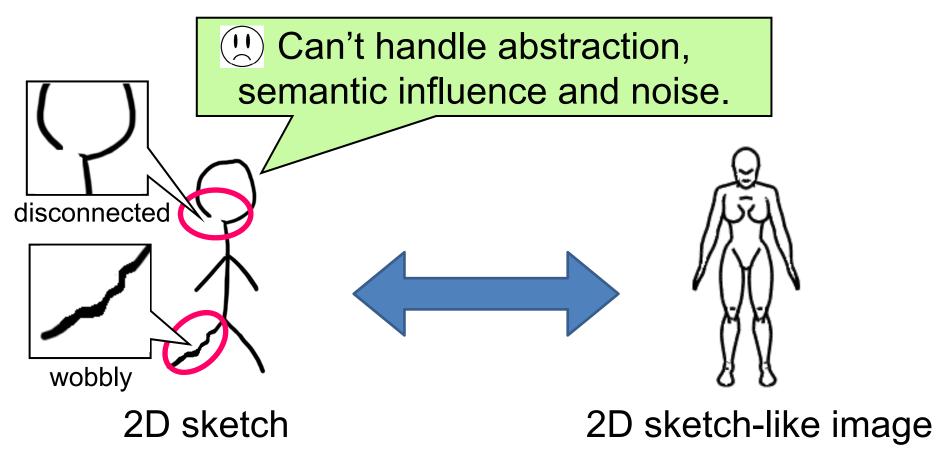
Approach 1 : Image feature-based comparison.

- Renders 3D models into lines.
  - e.g., Suggestive contour [DeCarlo03], ...
- Adopted by most.

U Can be compared.
 Compared.

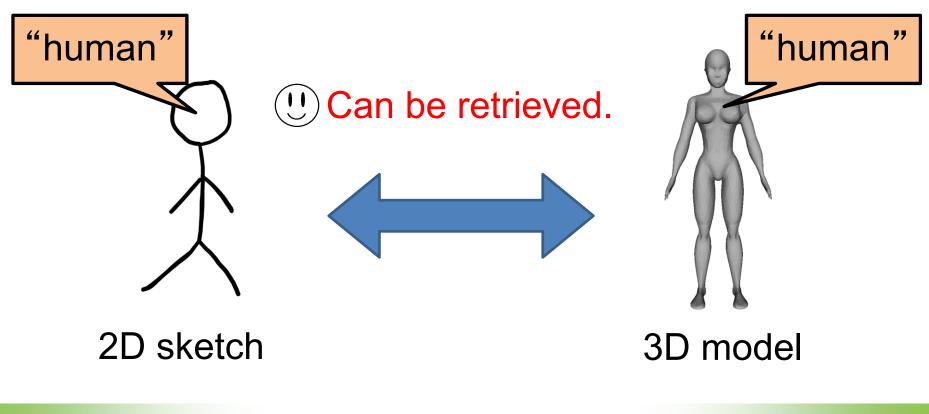


Approach 1 : Image feature-based comparison.





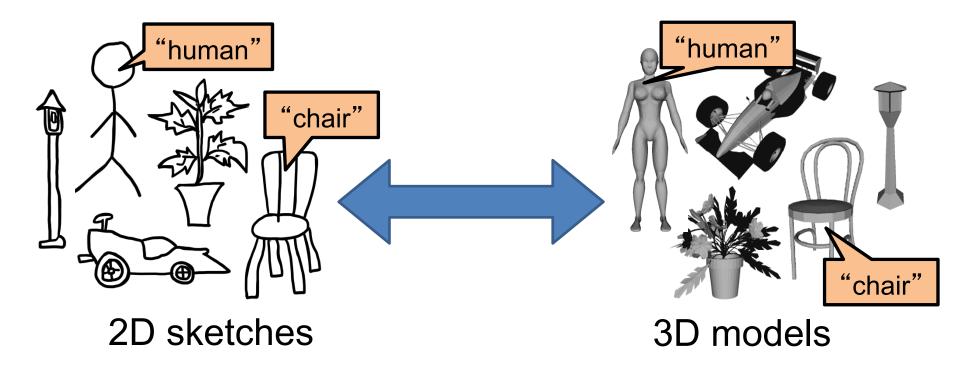
Approach 2 : Semantic label-based comparison.





Approach 2 : Semantic label-based comparison.

(!!) Learning sparse labels is difficult.

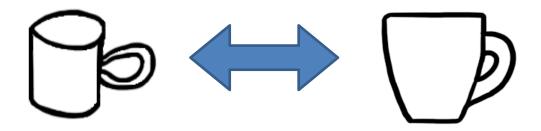


#### Our approach

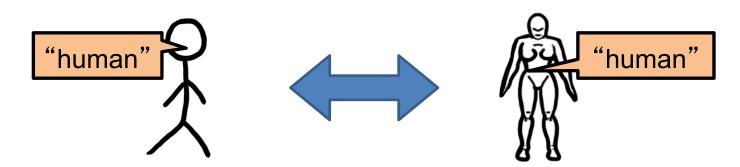


Combination of features and labels.

✓ Matching by image features.



✓ Matching by semantic labels.



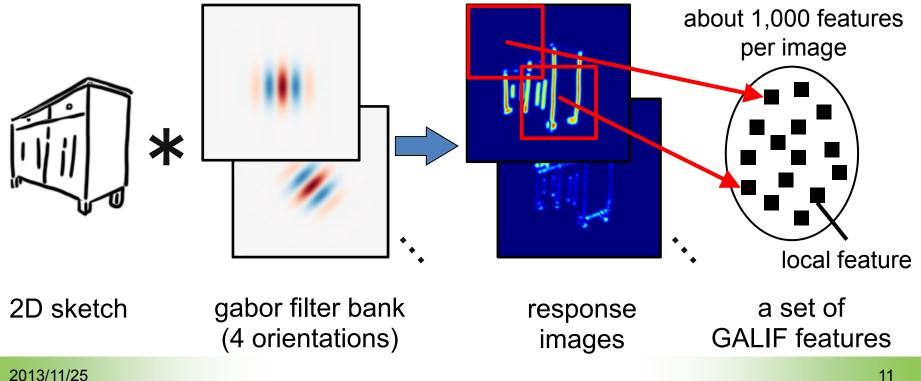
#### Outline

- Related work
  - BF-GALIF [Eitz12]
    - Algorithm for sketch-based 3D model retrieval
  - Manifold Ranking [Zhou03]
    - Algorithm for distance metric learning
- Proposed method
- Experiments and results
- Conclusion and future work

Related work : Sketch-to-3D model matching algorithm **BF-GALIF** [Eitz12]

#### Efficiently compares sets of local features.

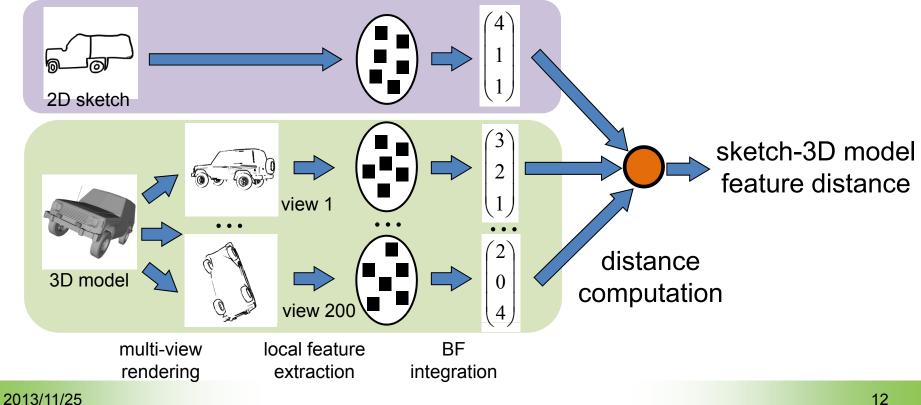
- 1. Densely extracts Gabor filter-based local features.
- 2. Integrates local features into a vector by Bag-of-Features.



Related work : Sketch-to-3D model matching algorithm **BF-GALIF** [Eitz12]

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Related work : Sketch-to-3D model matching algorithm BF-GALIF [Eitz12]



Efficiently compares sets of local features.

Robust against articulation of 2D shape.

Among the most accurate methods.

(!) Yet, insufficient ...

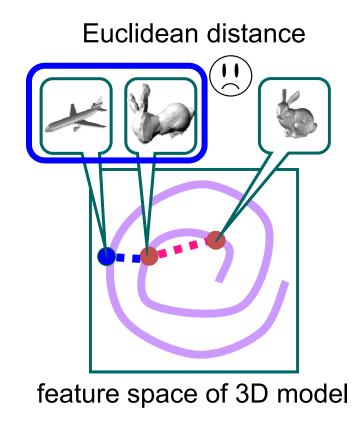
Our approach

- better feature comparison.
- semantic labels.

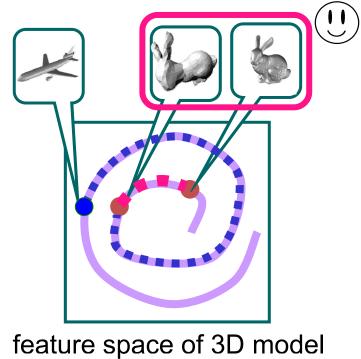
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#### Improving single-domain feature comparison



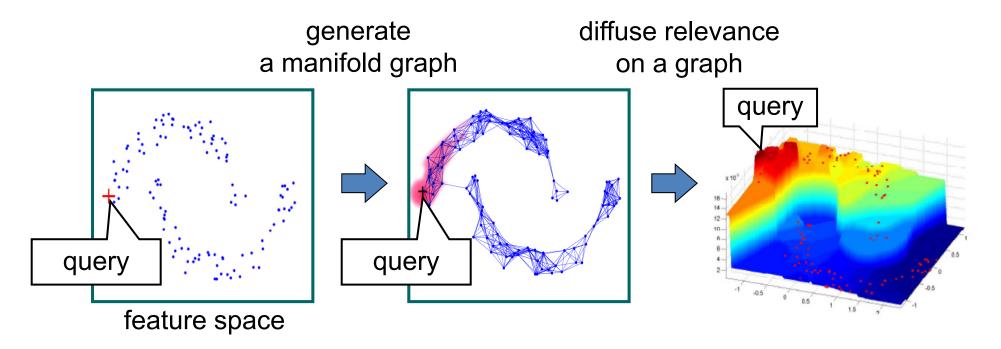


feature-adaptive distance



Related work : Distance metric learning Manifold Ranking [Zhou03] 7

Diffusion distance on a feature manifold graph.



#### Our approach

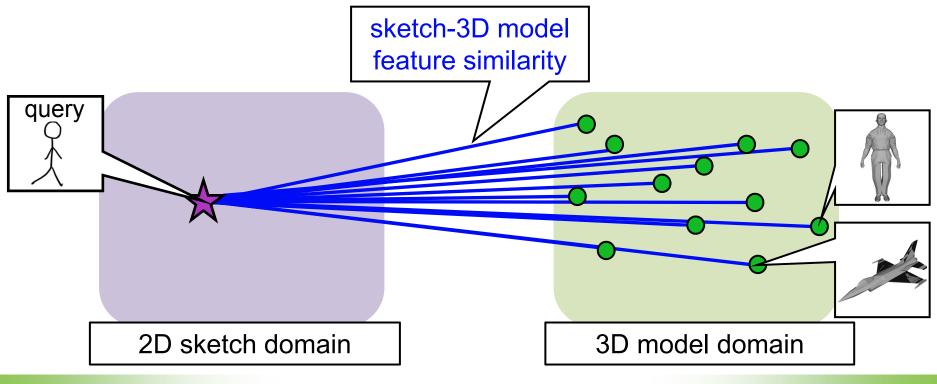
extends Manifold Ranking to cross-domain.

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# >

#### BF-GALIF [Eitz12]

#### – (!) Structure of feature manifold is ignored.



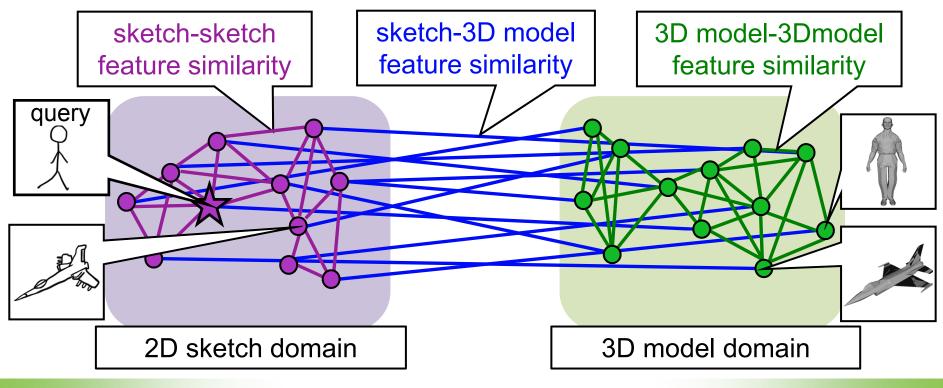
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- Proposed method
  - Cross-Domain Manifold Ranking (CDMR) algorithm
- Experiments and results
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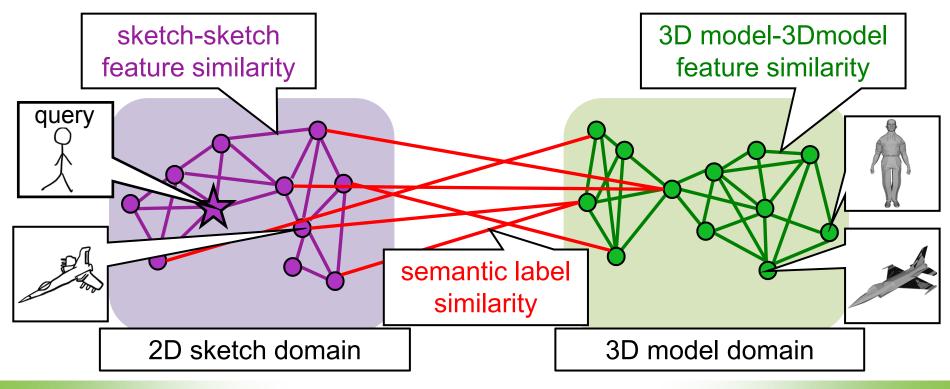


- Ranking by diffusion distance on a Cross-Domain Manifold (CDM).
  - $\bigcirc$  Structure of each feature manifold is kept.



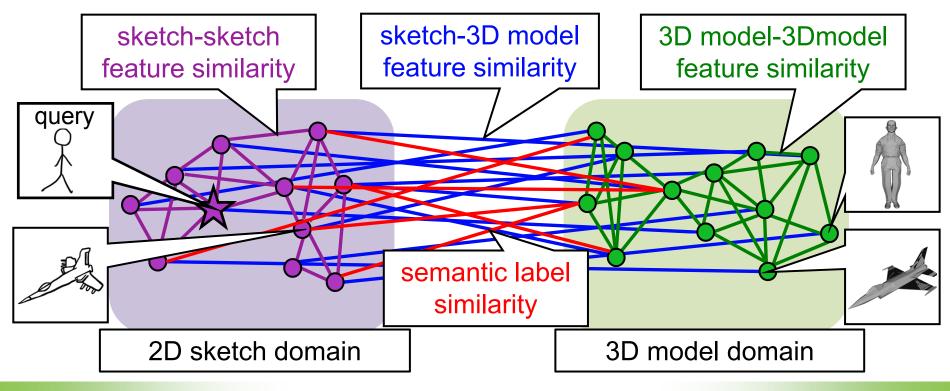


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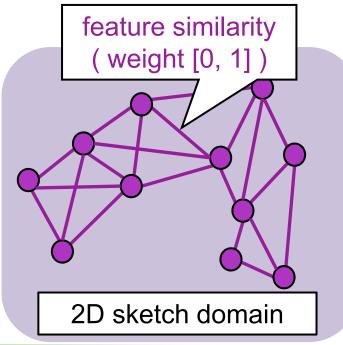


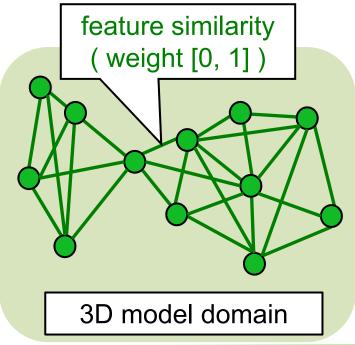


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- Ranking by diffusion distance on the CDM.
  - 1. Generates a feature manifold on each domain.
  - 2. Links the two manifolds by feature and label similarity.
  - 3. Diffuses relevance from the query.

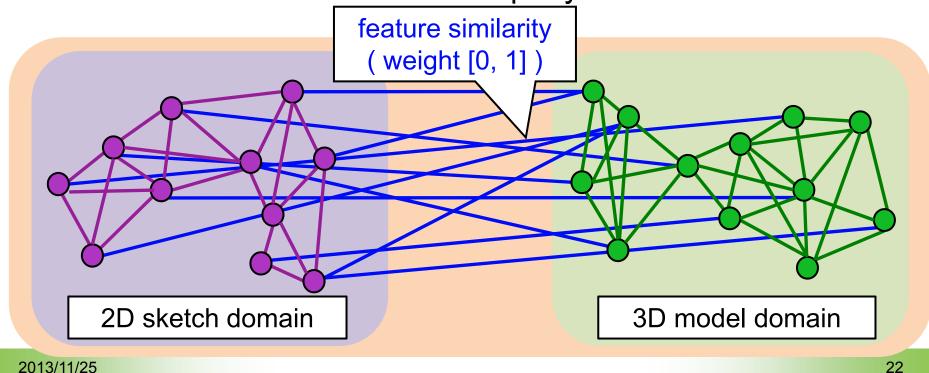




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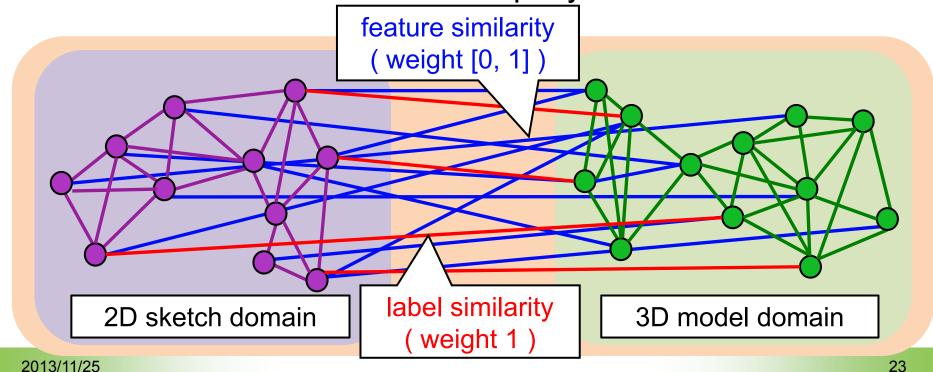
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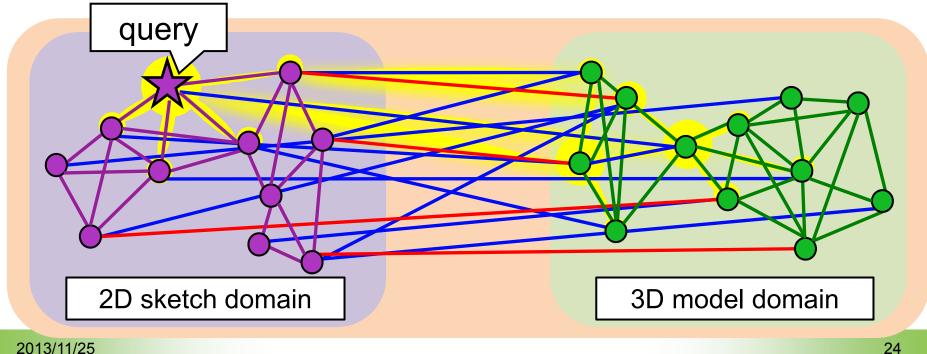


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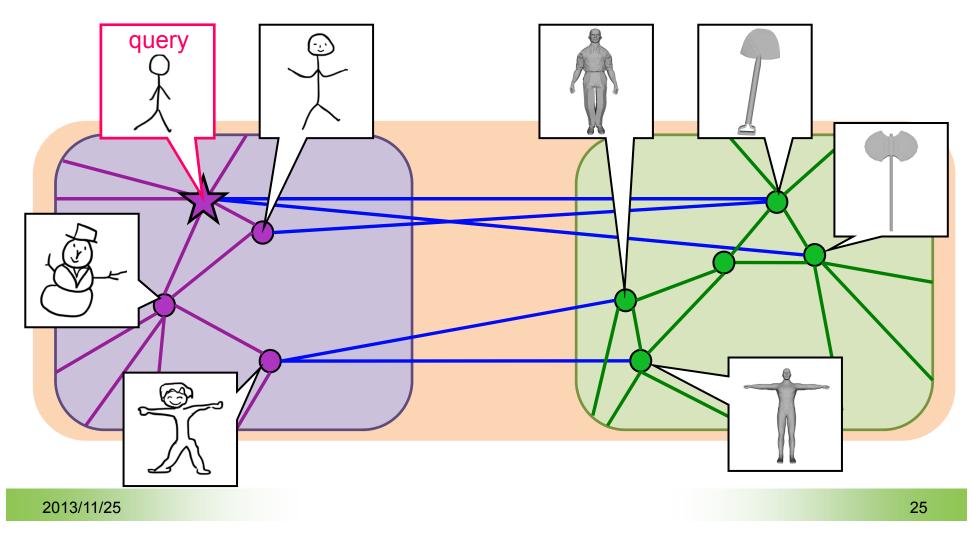
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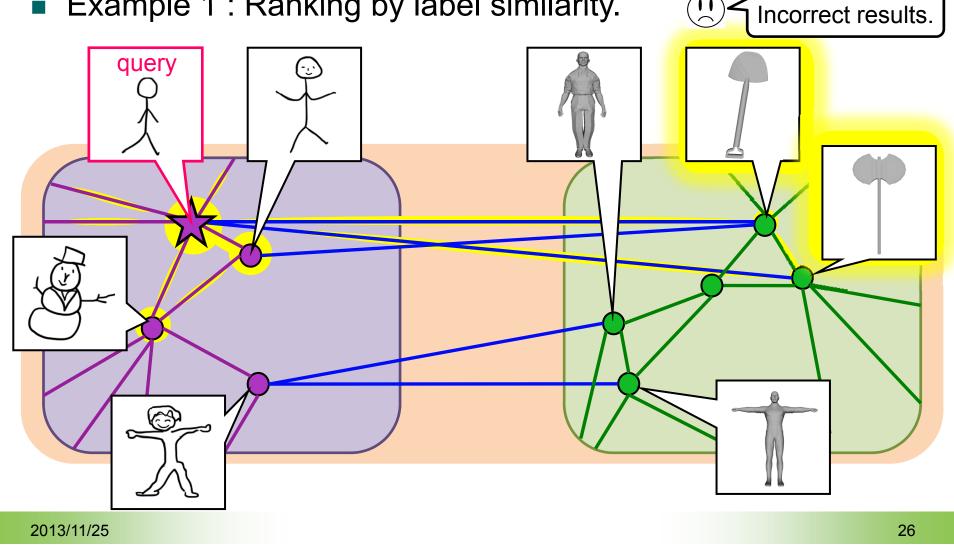


• Example 1 : Ranking by label similarity.

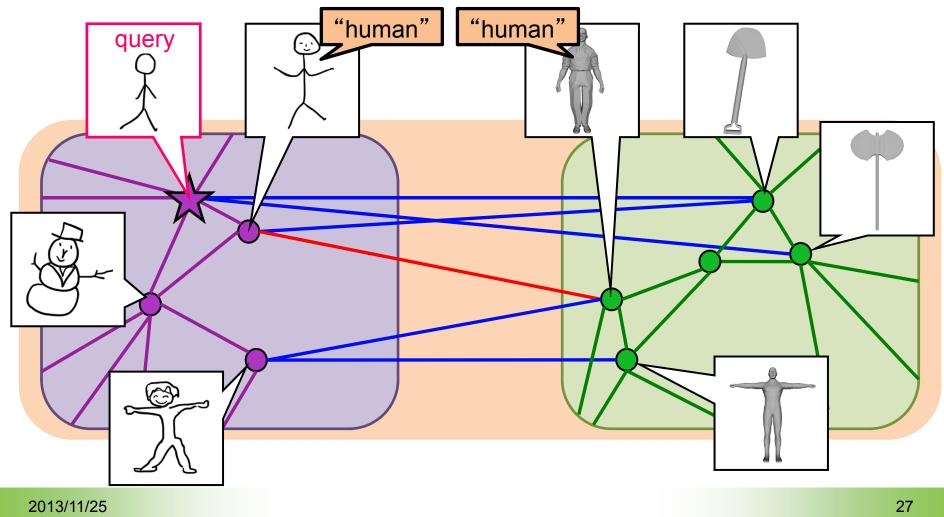




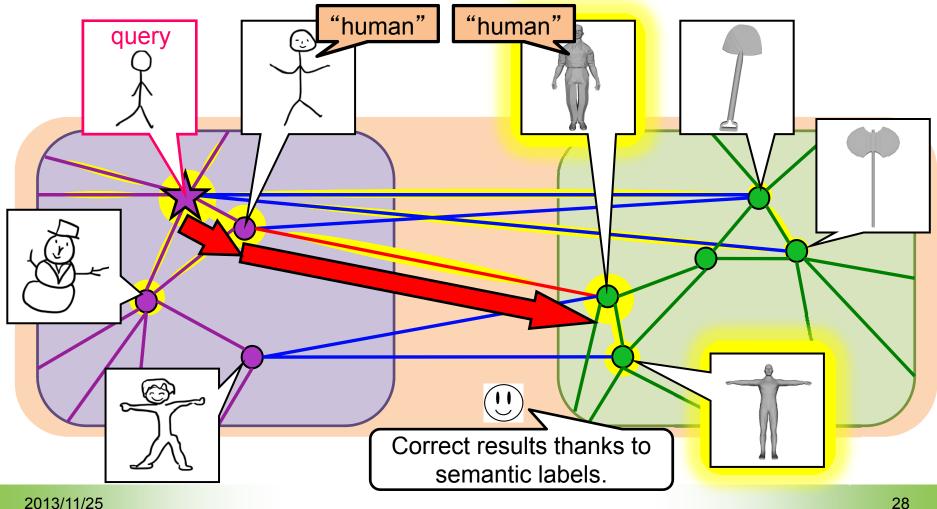
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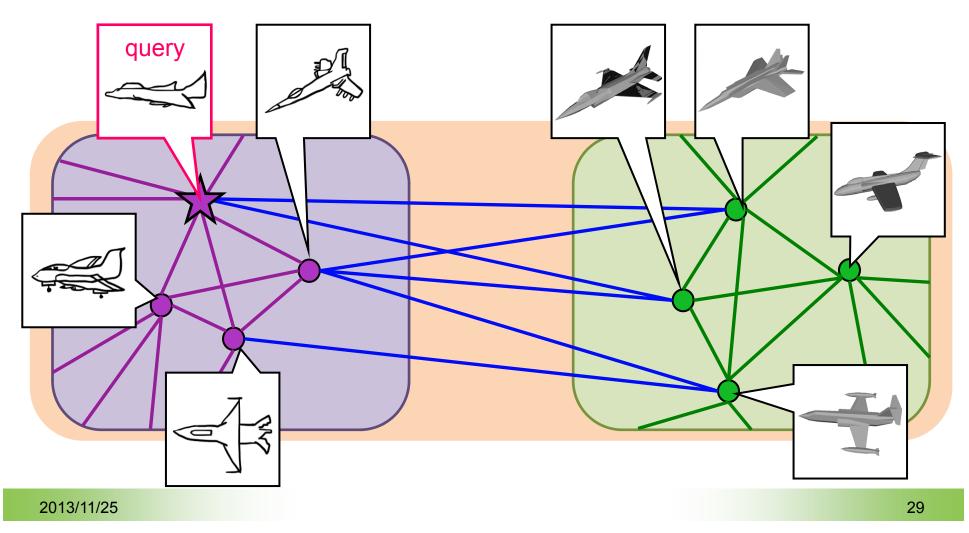
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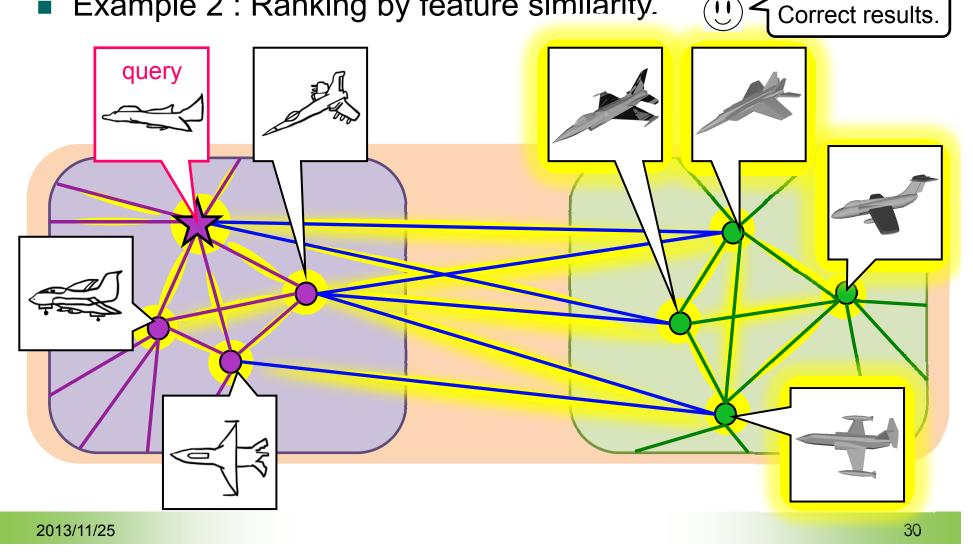
Example 1 : Ranking by label similarity.



• Example 2 : Ranking by feature similarity.

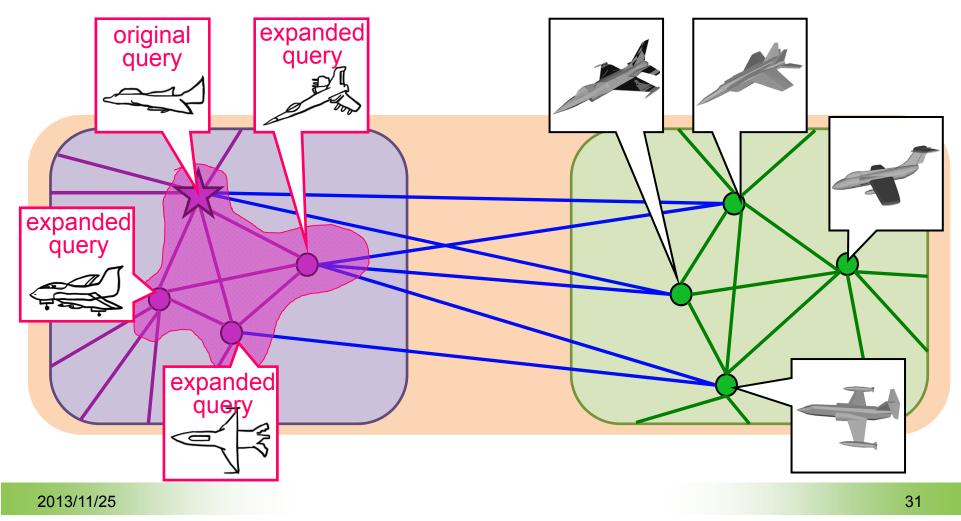


Example 2 : Ranking by feature similarity.  $\bigcirc$ 



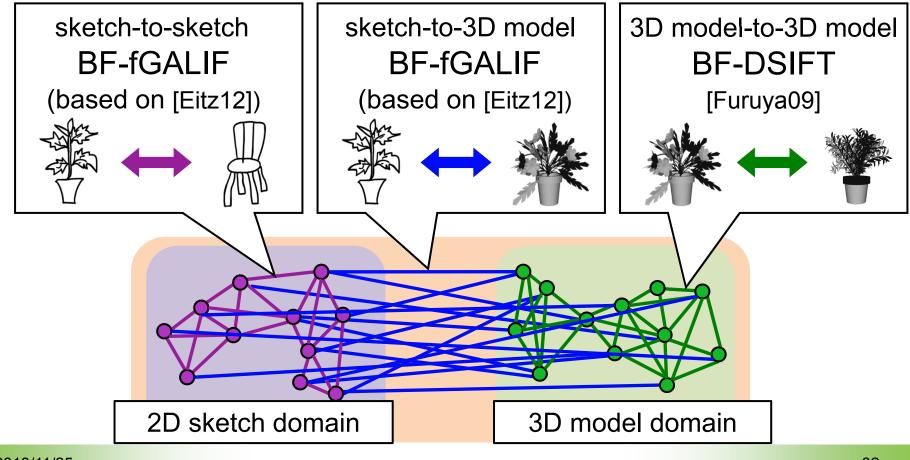


CDMR embodies an automatic query expansion.





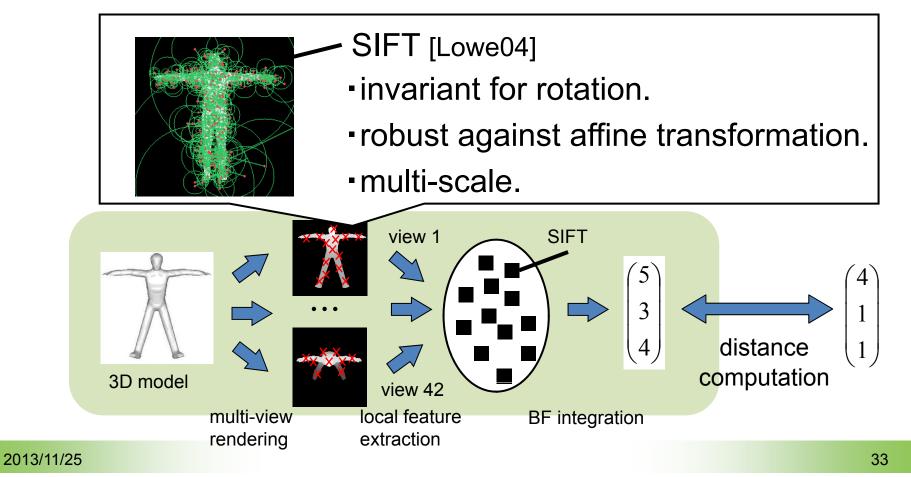
#### Feature comparison methods.



#### 3D model-to-3D model comparison BF-DSIFT [Furuya09]



- Dense and random extraction of local visual features.
- Per-model BF integration.



#### Outline

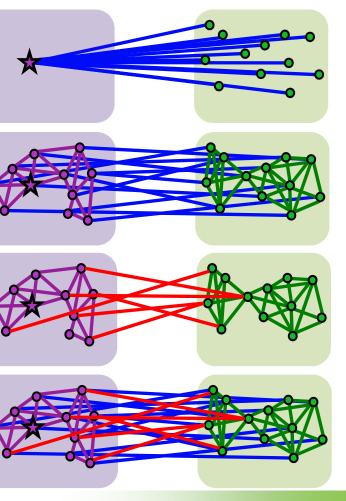
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#### Experiments

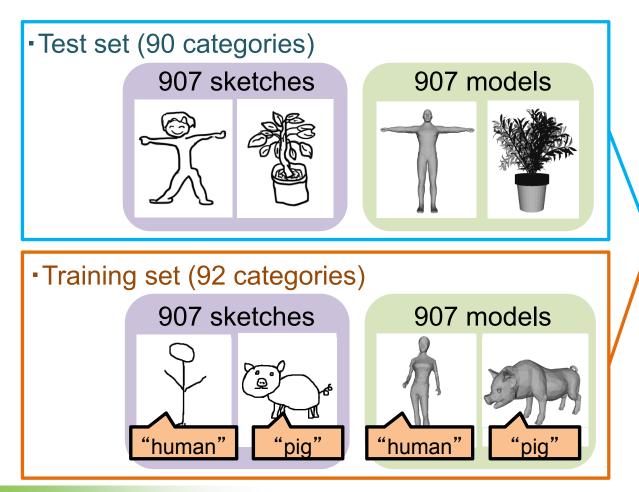
- Evaluate retrieval accuracy.
  - BF-fGALIF (≒[Eitz12])
    - No distance metric learning.
    - Baseline
  - CDMR-BF-fGALIF (F)
    - Unsupervised learning.
  - CDMR-BF-fGALIF (L)
    - Supervised learning.
  - CDMR-BF-fGALIF (F+L)
    - Semi-supervised learning.





#### Experiments Benchmark databases





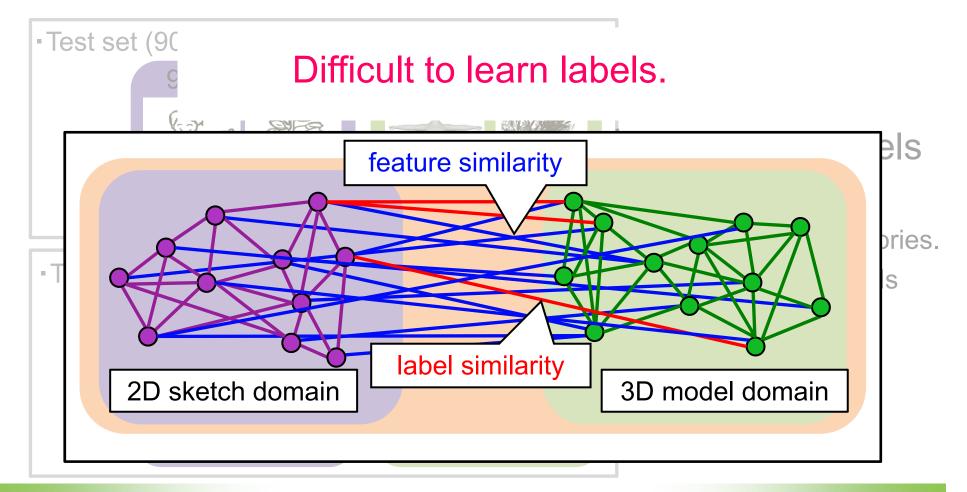
## Difficult to learn labels.

- 21 shared categories.
- As few as 4 labels per category.

# Experiments Benchmark databases



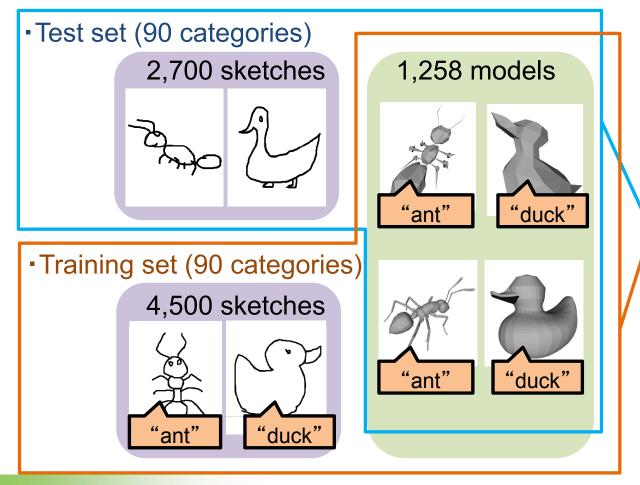
S-PSB [Eitz12]



#### Experiments Benchmark databases



SHREC2013 sketch-based 3D shape retrieval (SH13) [Li13]

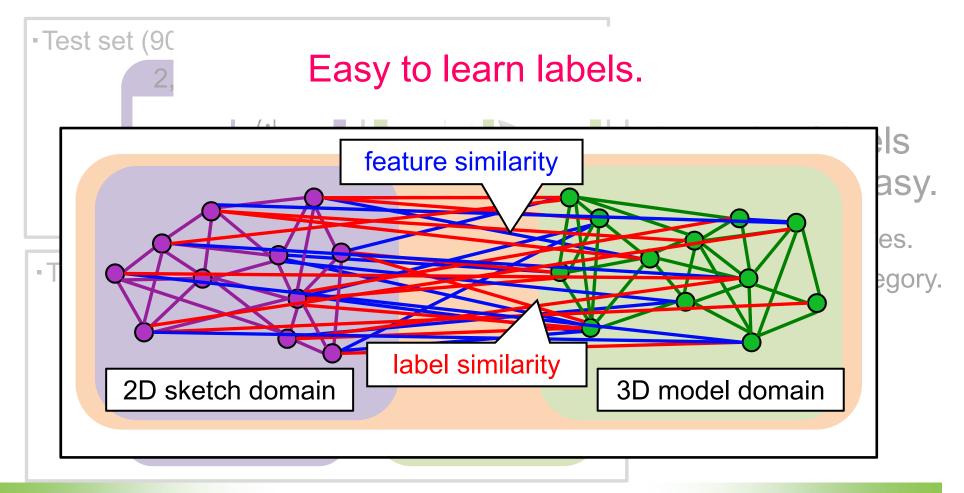


# Easy to learn labels.

- share all categories.
- 50 labels per category.

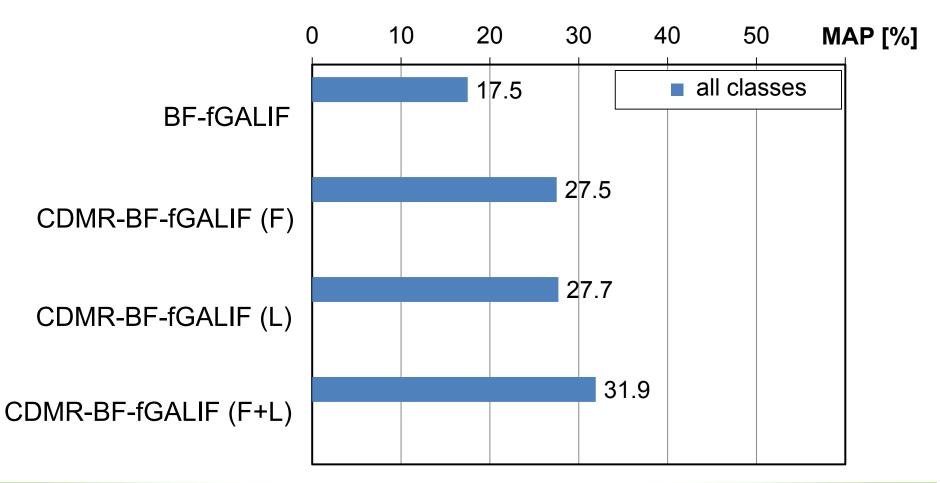
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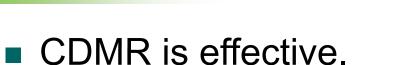
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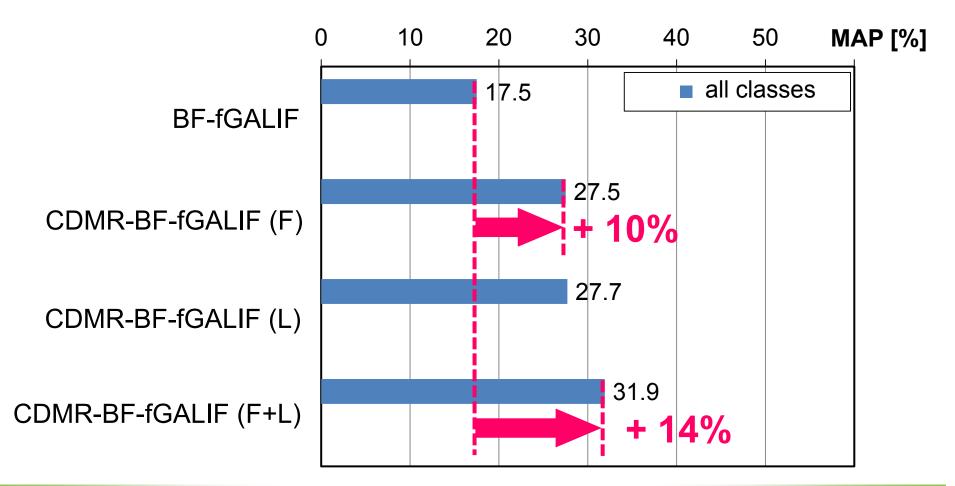


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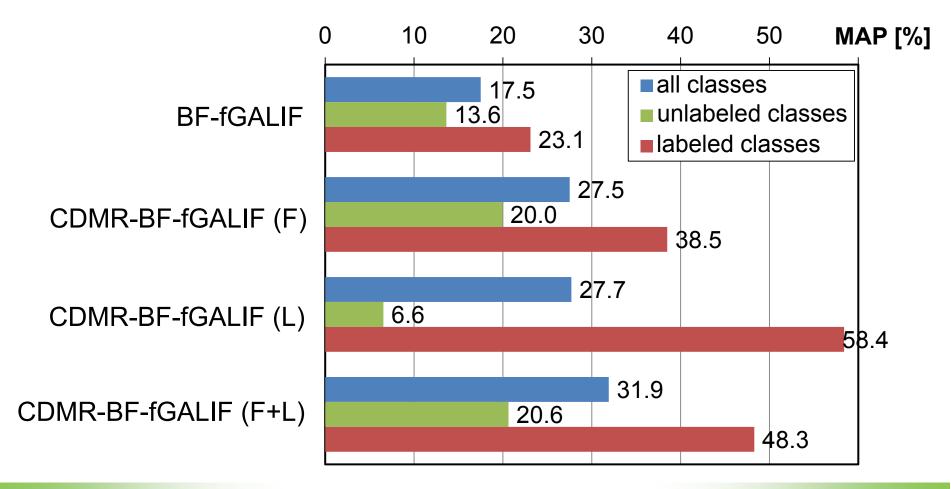






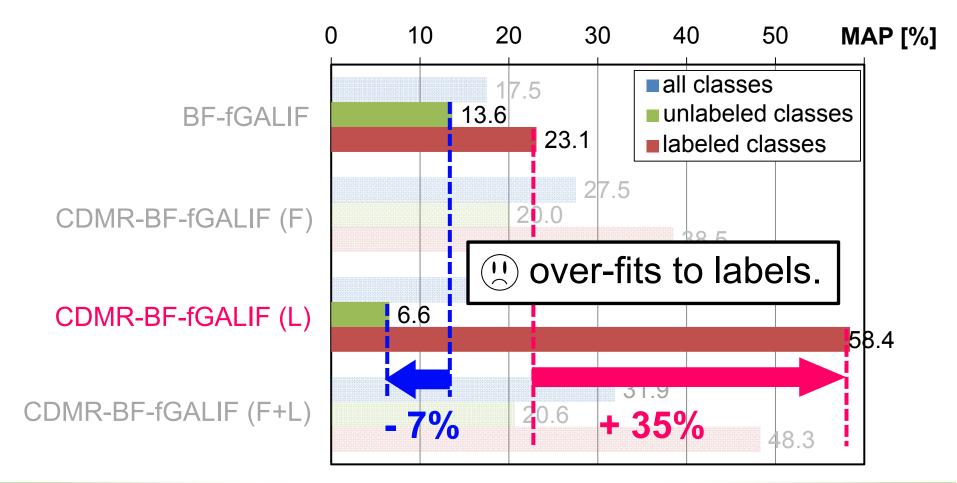


CDMR (F+L) effectively learns sparse labeling.



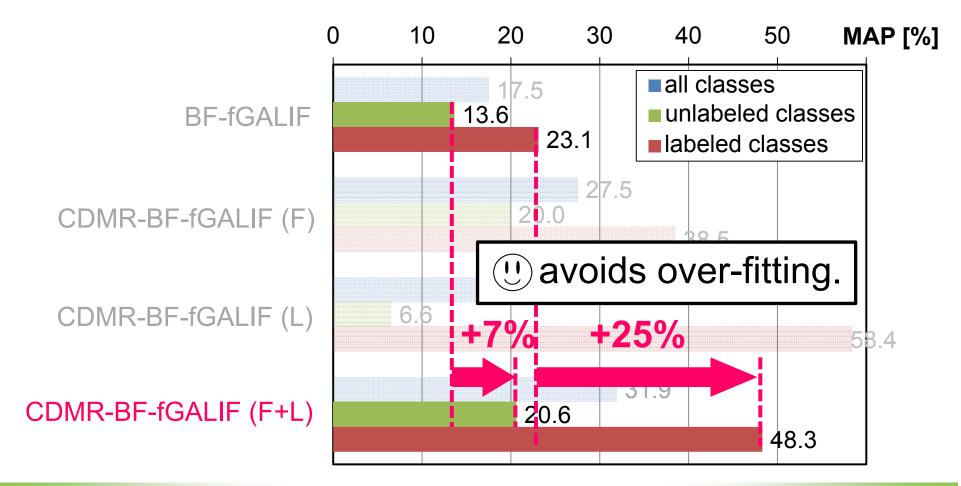


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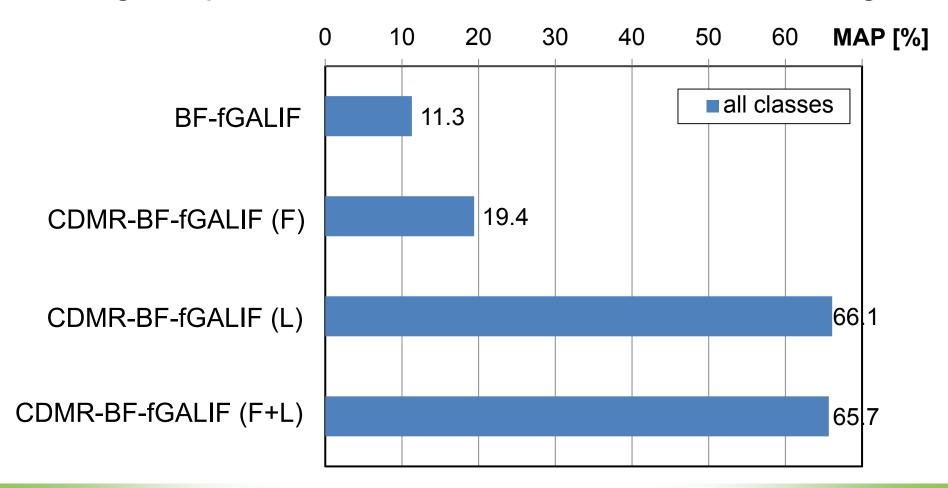


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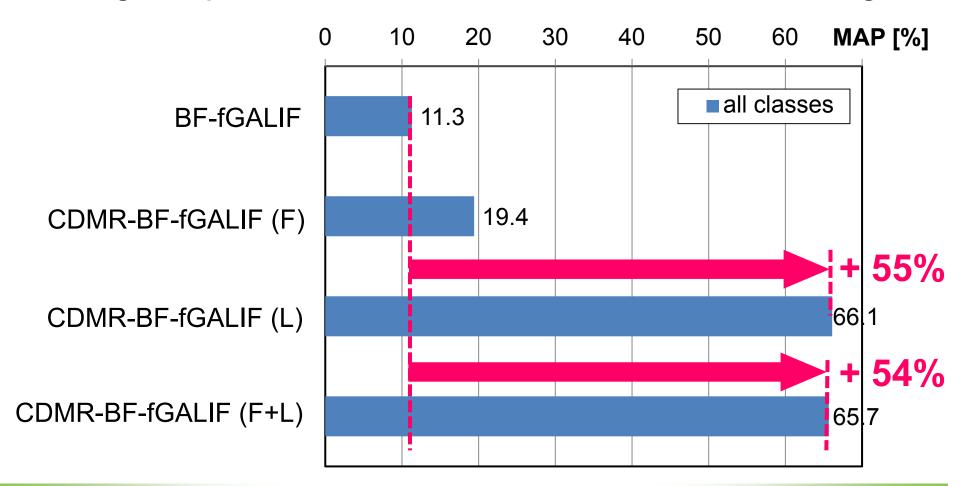


Large improvement of MAP due to dense labeling.

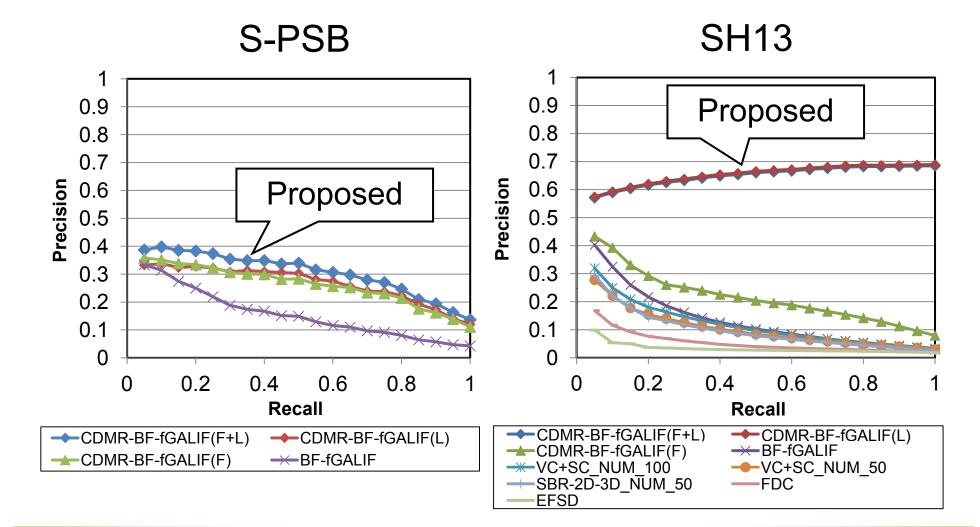




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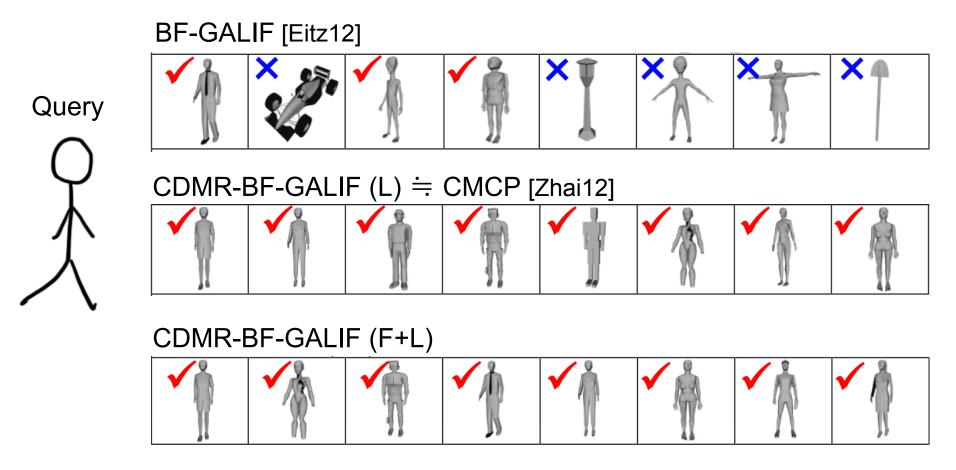
#### Experimental results Comparison with other algorithms



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# Experimental results Retrieval results (S-PSB)

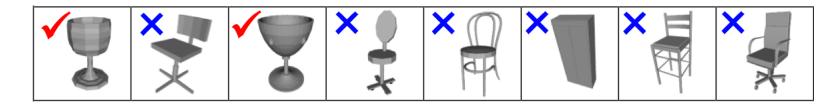
"human" (labeled category)



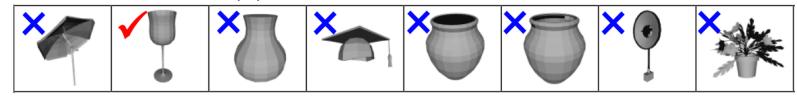
#### Experimental results Retrieval results (S-PSB)

"glass\_with\_stem" (unlabeled category)

BF-GALIF [Eitz12]



CDMR-BF-GALIF (L)  $\doteqdot$  CMCP [Zhai12]



CDMR-BF-GALIF (F+L)



Query

#### Experimental results Computation time per query



Computation time per query for S-PSB [s]

methods	extract BF-GALIF	compute distance	CDMR (matrix size : 3,628 x 3,628)	total	
BF-GALIF	0.11	1.59		1.70	
CDMR-BF-GALIF	0.11	1.59	36.86	38.56	

#### Computation time per query for SH13 [s]

methods	extract BF-GALIF	compute Distance	CDMR (matrix size : 8,458 x 8,458)	total	
BF-GALIF	0.11	1.13		1.24	
CDMR-BF-GALIF	0.11	1.17	659.93	661.21	

measured by using: Intel Xeon E3-1245 @ 3.30 GHz, 32 GB of memory

#### **Conclusion and Future work**



#### Conclusion

- More accurate sketch-based 3D model retrieval.
  - Cross-Domain Manifold Ranking (CDMR)
    - Combines feature similarity and semantic similarity.
    - Outperforms previous methods.
- Future work
  - Faster computation (e.g., approximation of diffusion).
  - More accurate feature comparison.